Better Code: Concurrency

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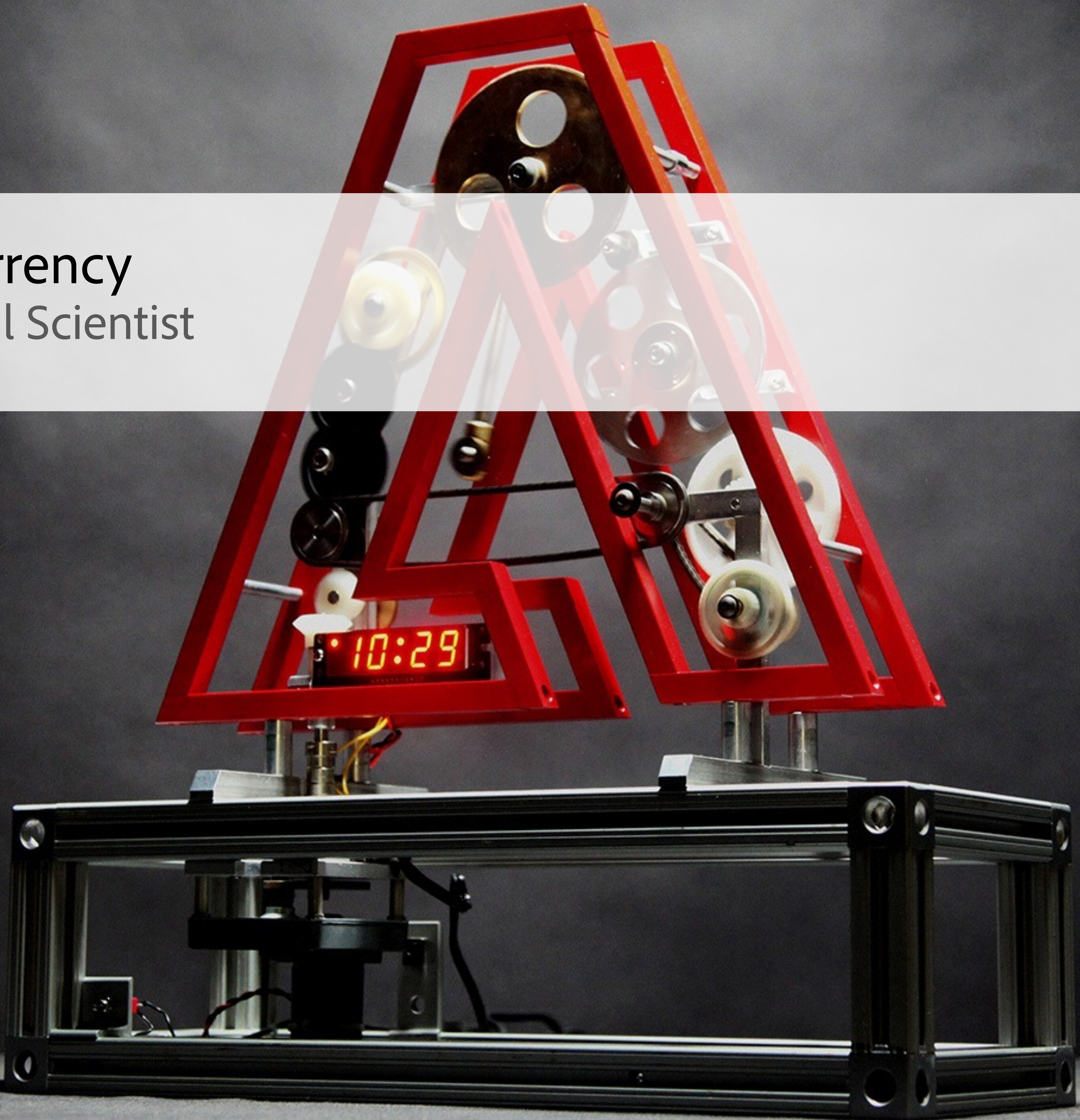

Bē
Evolution Bureau

Better Code

- Regular Type
  - Goal: Implement Complete and Efficient Types
- Algorithms
  - Goal: No Raw Loops
- Data Structures
  - Goal: No Incidental Data Structures
- Runtime Polymorphism
  - Goal: No Raw Pointers
- Concurrency
  - Goal: No Raw Synchronization Primitives
- …

Common Themes

- Manage Relationships
- Understand the Fundamentals
- Code Simply

Demo

Concurrency

- Concurrency: when tasks start, run, and complete in overlapping time periods
- Parallelism: when two or more tasks execute simultaneously

- Why?
  - Enable performance through parallelism
  - Improve interactivity by handling user actions concurrent with processing and IO

http://docs.oracle.com/cd/E19455-01/806-5257/6je9h032b/index.html

No Raw Synchronization Primitives

What are raw synchronization primitives?

- Synchronization primitives are basic constructs such as:
  - Mutex
  - Atomic
  - Semaphore
  - Memory Fence
  - Condition Variable

You Will Likely Get It Wrong

Problems with Locks

```
template <typename T>
class bad_cow {
    struct object_t {
        explicit object_t(const T& x) : data_m(x) { ++count_m; }
        atomic<int> count_m;
        T           data_m; };
    object_t* object_m;
 public:
    explicit bad_cow(const T& x) : object_m(new object_t(x)) { }
    ~bad_cow() { if (0 == --object_m->count_m) delete object_m; }
    bad_cow(const bad_cow& x) : object_m(x.object_m) { ++object_m->count_m; }

    bad_cow& operator=(const T& x) {
        if (object_m->count_m == 1) object_m->data_m = x;
        else {
            object_t* tmp = new object_t(x);
            --object_m->count_m;
            object_m = tmp;
        }
        return *this;
    }
};
```

- There is a subtle race condition here:
  - if count != 1 then the bad_cow could also is owned by another thread(s)
  - if the other thread(s) releases the bad_cow between these two atomic operations
  - then our count will fall to zero and we will leak the object

Problems with Locks

```
template <typename T>
class bad_cow {
    struct object_t {
        explicit object_t(const T& x) : data_m(x) { ++count_m; }
        atomic<int> count_m;
        T           data_m; };
    object_t* object_m;
 public:
    explicit bad_cow(const T& x) : object_m(new object_t(x)) { }
    ~bad_cow() { if (0 == --object_m->count_m) delete object_m; }
    bad_cow(const bad_cow& x) : object_m(x.object_m) { ++object_m->count_m; }

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        else {
            object_t* tmp = new object_t(x);
            if (0 == --object_m->count_m) delete object_m;
            object_m = tmp;
        }
        return *this;
    }
};
```
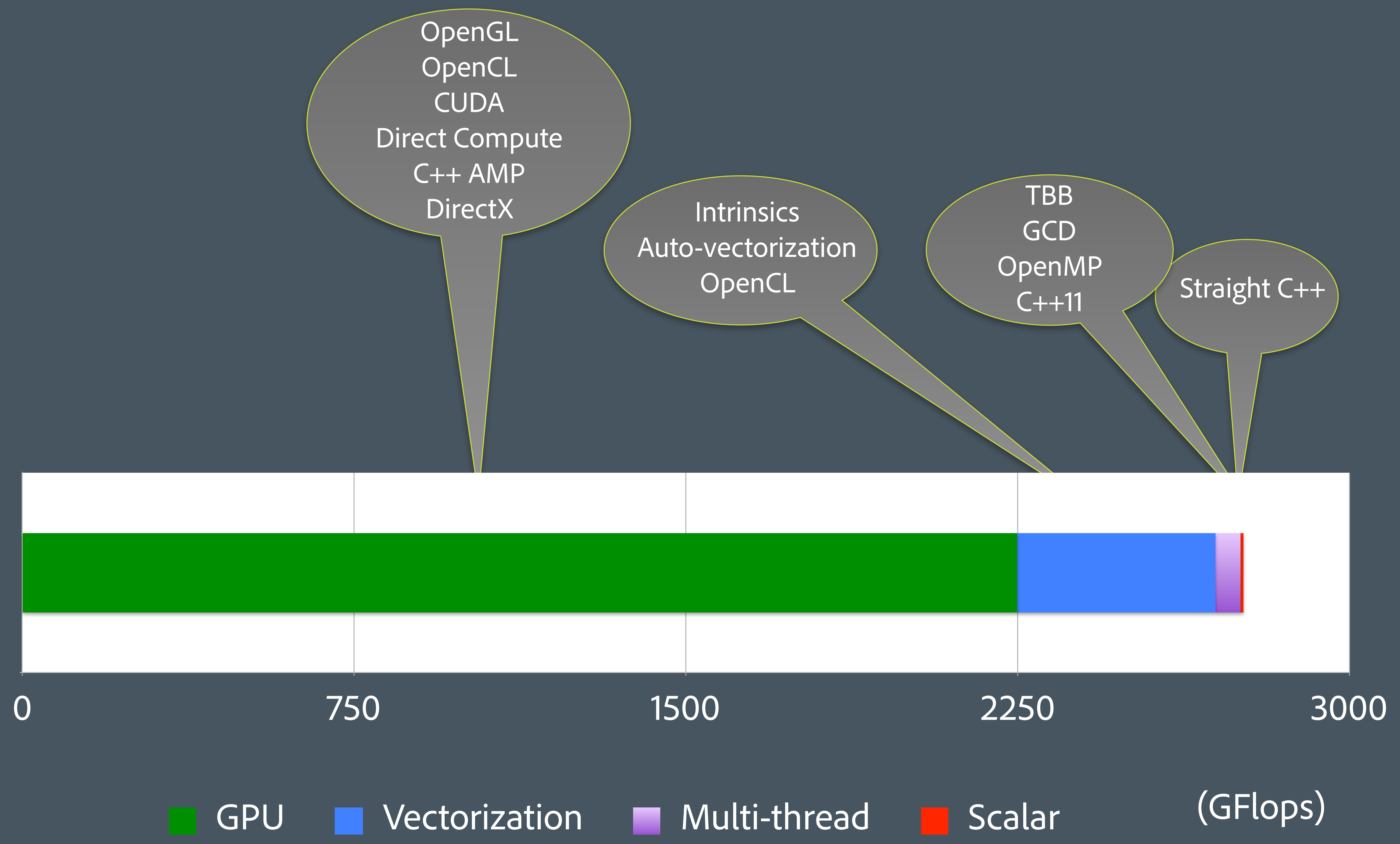
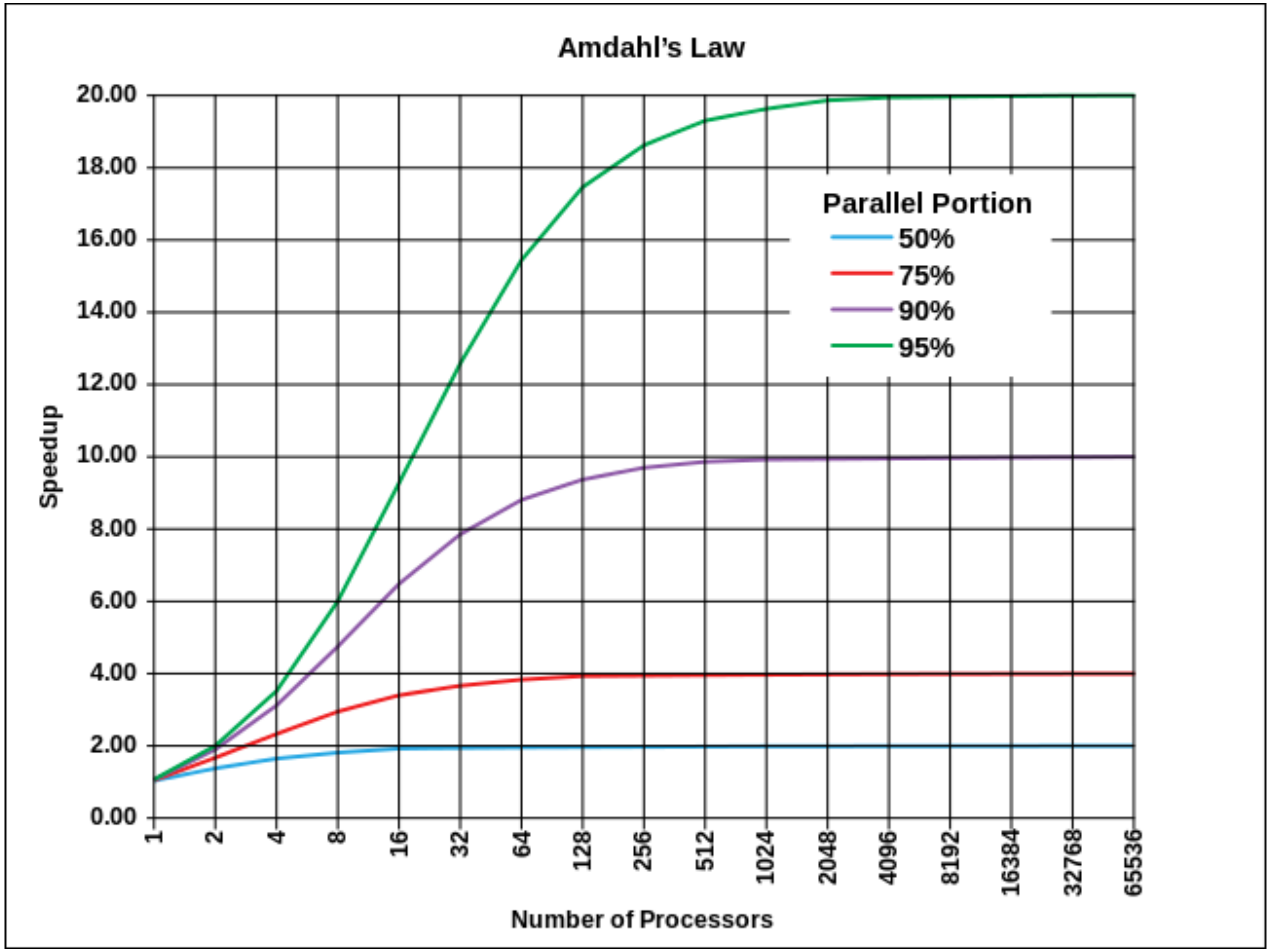

Performance through Parallelism

Desktop Compute Power (8-core 3.5GHz Sandy Bridge + AMD Radeon 6950)



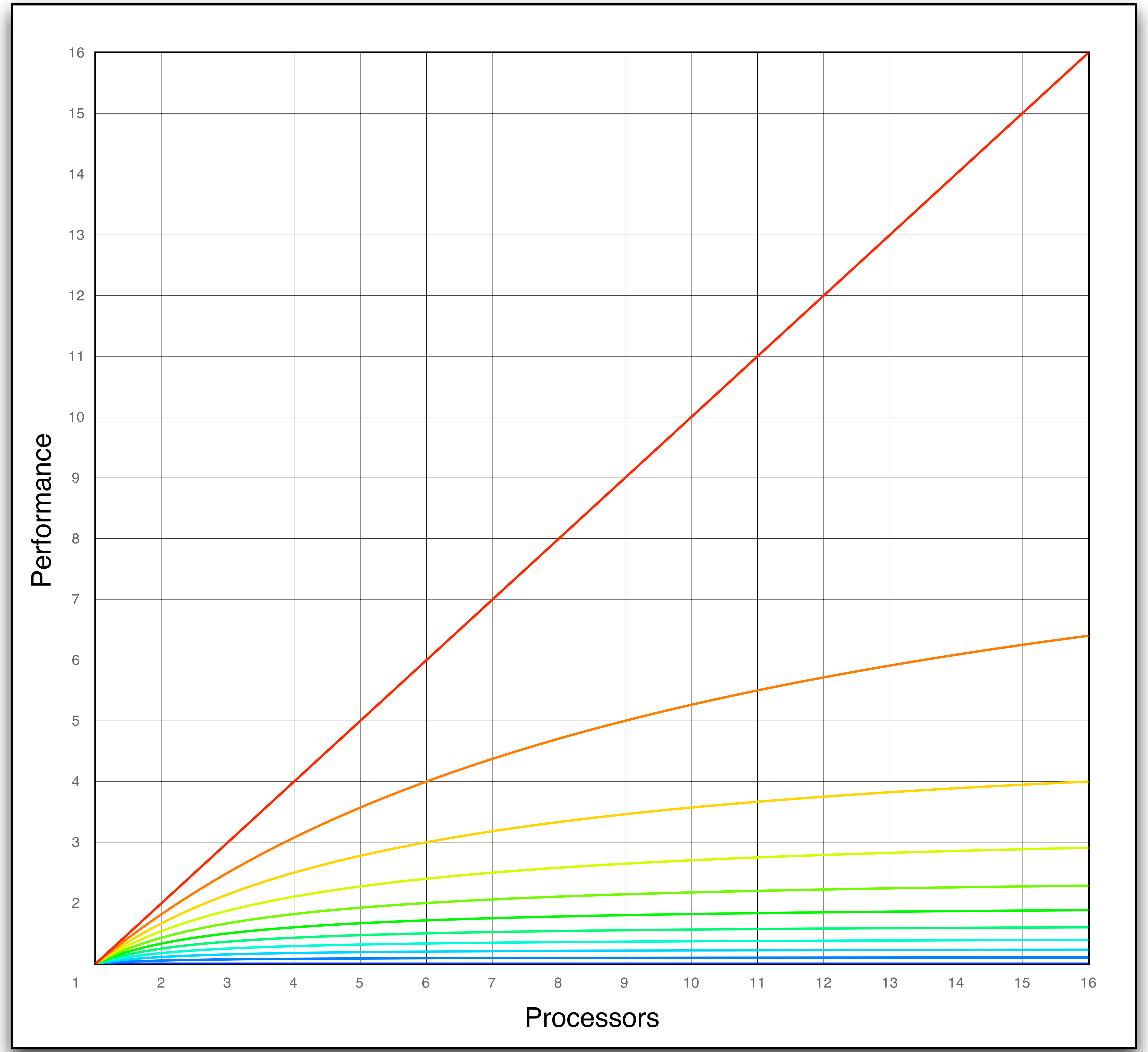
Amdahl's Law

$$S(N) = \frac{1}{(1-P) + \frac{P}{N}}$$



http://en.wikipedia.org/wiki/Amdahl%27s_law

Amdahl's Law

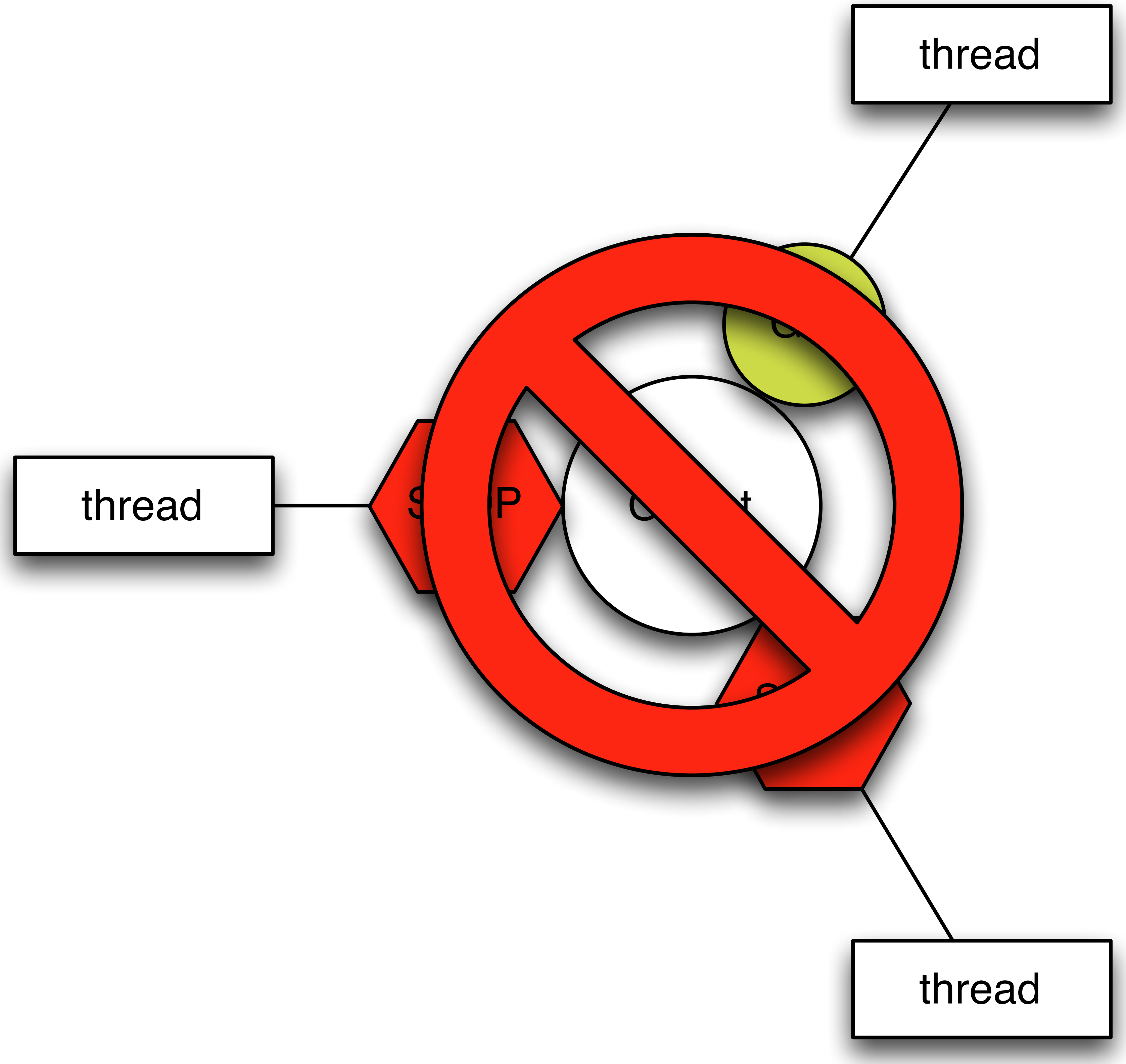


Performance
Processors
16
15
14
13
12
11
10
9
8
7
6
5
4
3
2
1
2
3
4
5
6
7
8
9
10
11
12
13
14
15
16

What Makes It Slow

- Starvation
- Latency
- Overhead
- Wait

Why No Raw Synchronization Primitives?



Minimize Locks

Threads and Tasks

- Thread: Execution environment consisting of a stack and processor state running in parallel to other threads
- Task: A unit of work, often a function, to be executed on a thread

- Tasks are scheduled on a thread pool to optimize machine utilization

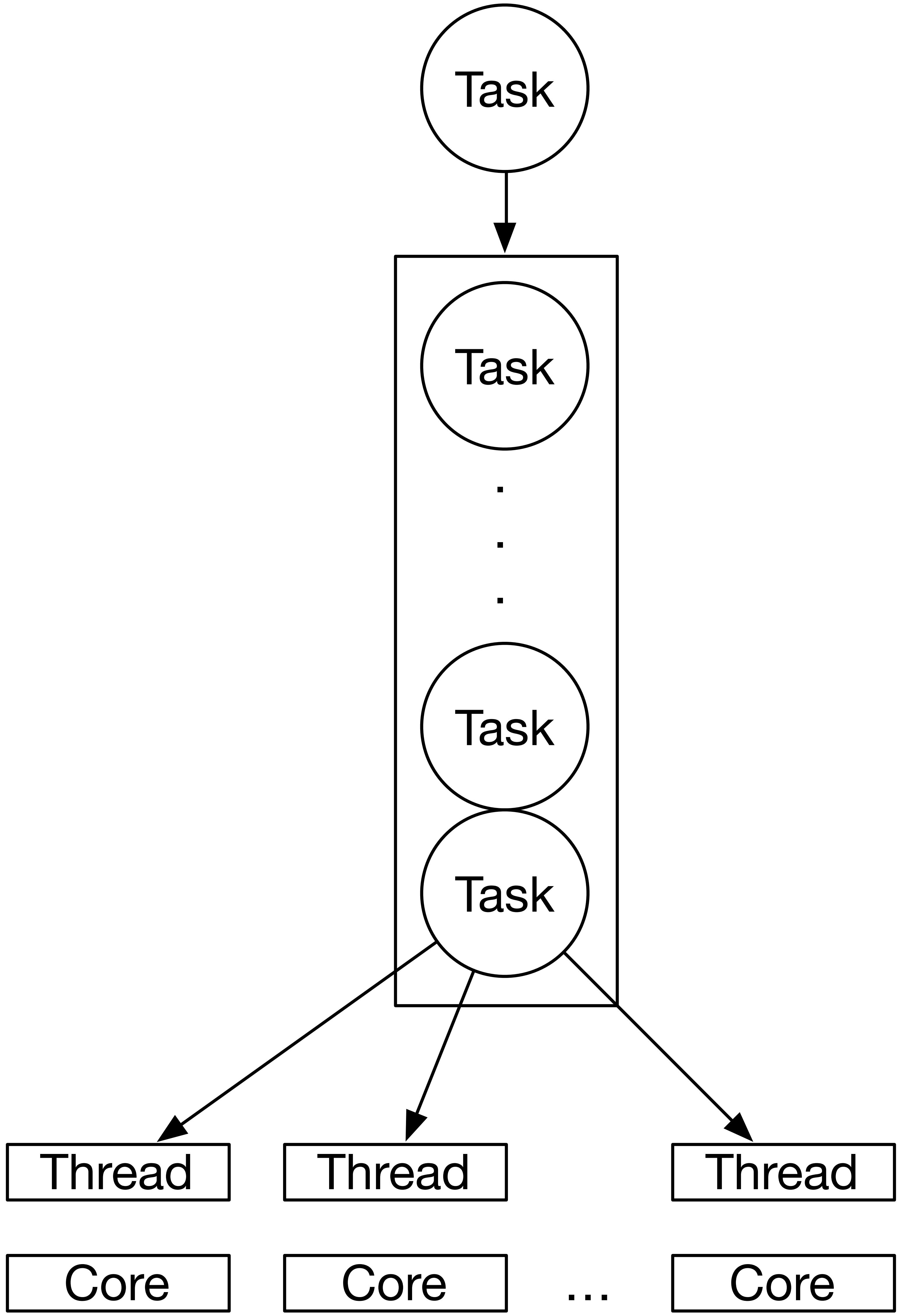
C++14 and Tasks

- C++14 does not have a task system
  - Threads
  - Futures

Building a Task System

- Portable Reference Implementation in C++14
  - Windows - Window Thread Pool and PPL
  - Apple - Grand Central Dispatch (libdispatch)
    - open source, runs on Linux and Android
  - Intel TBB - many platforms
    - open source
  - HPX - many platforms
    - open source

Building a Task System



http://docs.oracle.com/cd/E19253-01/816-5137/ggedn/index.html

Building a Task System

```
using lock_t = unique_lock<mutex>;

class notification_queue {
    deque<function<void()>> _q;
    mutex                   _mutex;
    condition_variable      _ready;

  public:
    void pop(function<void()>& x) {
        lock_t lock{_mutex};
         while (_q.empty()) _ready.wait(lock);
         x = move(_q.front());
        _q.pop_front();
    }

    template<typename F>
    void push(F&& f) {
        {
            lock_t lock{_mutex};
            _q.emplace_back(forward<F>(f));
        }
        _ready.notify_one();
    }
};
```


Adobe

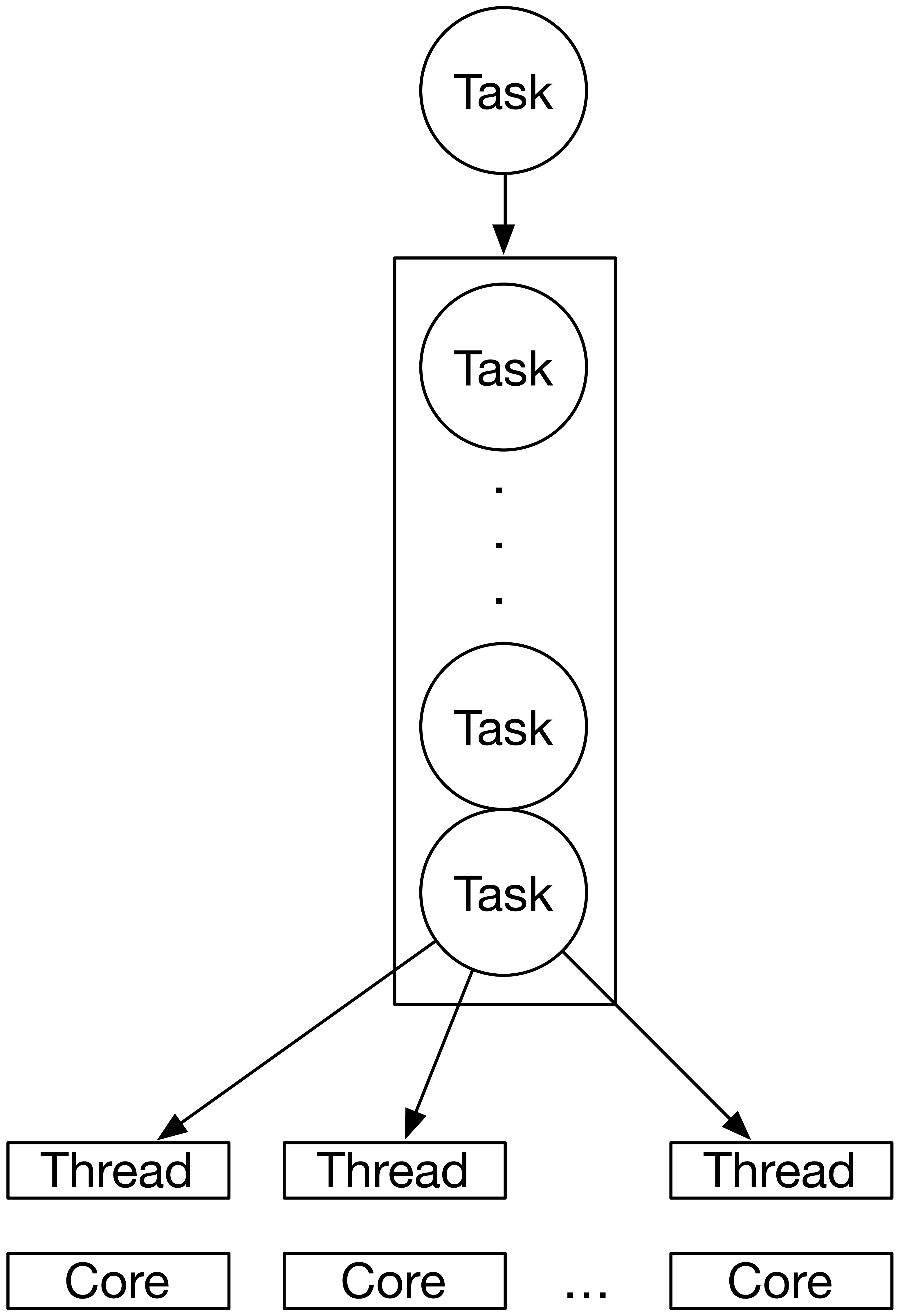
Building a Task System

```
class task_system {
    const unsigned              _count{thread::hardware_concurrency()};
    vector<thread>              _threads;
    notification_queue          _q;

    void run(unsigned i) {
        while (true) {
            function<void()> f;
            _q.pop(f);
            f();
        }
    }

  public:
    task_system() {
        for (unsigned n = 0; n != _count; ++n) {
            _threads.emplace_back([&, n]{ run(n); });
        }
    }

    ~task_system() {
        for (auto& e : _threads) e.join();
    }

    template <typename F>
    void async_(F&& f) {
        _q.push(forward<F>(f));
    }
};
```

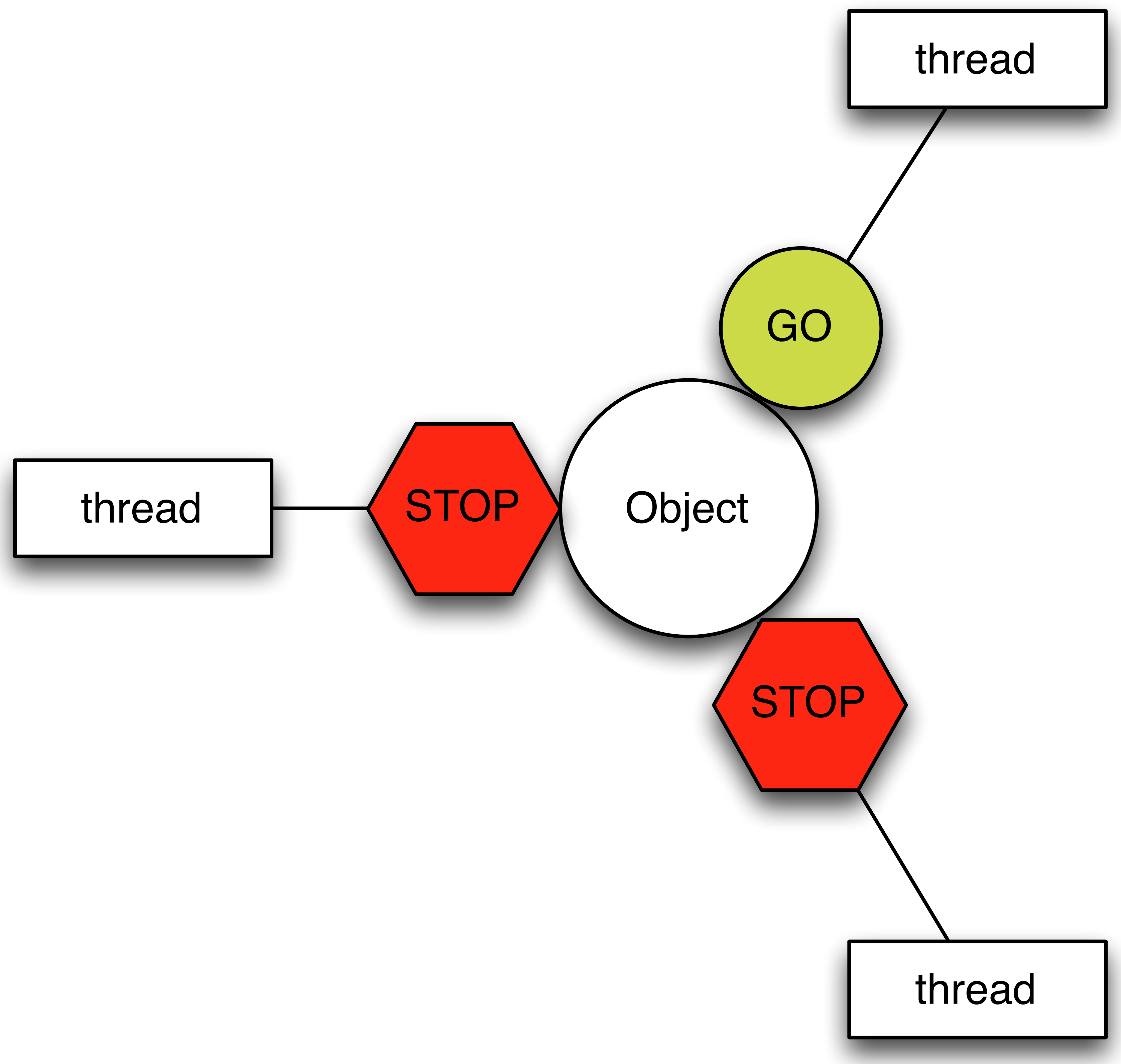
Building a Task System

```
class notification_queue {
    deque<function<void()>> _q;
    bool                    _done{false};
    mutex                   _mutex;
    condition_variable      _ready;

  public:
    void done() {
        {
            unique_lock<mutex> lock{_mutex};
            _done = true;
        }
        _ready.notify_all();
    }

    bool pop(function<void()>& x) {
        lock_t lock{_mutex};
         while (_q.empty() && !_done) _ready.wait(lock);
         if (_q.empty()) return false;
         x = move(_q.front());
        _q.pop_front();
        return true;
    }

    template<typename F>
    void push(F&& f) {
        {
            lock_t lock{_mutex};
             _q.emplace_back(forward<F>(f));
```

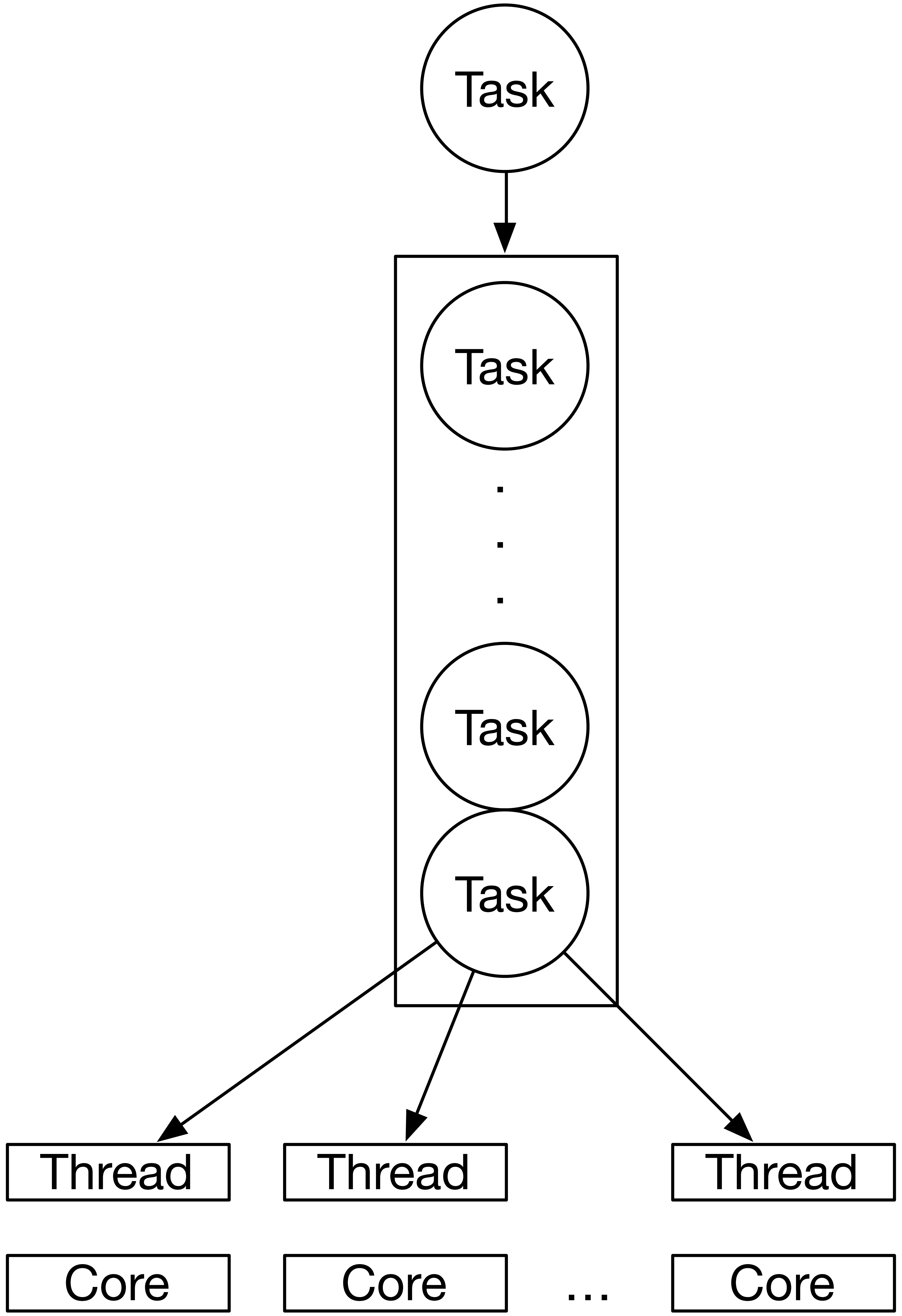
Building a Task System



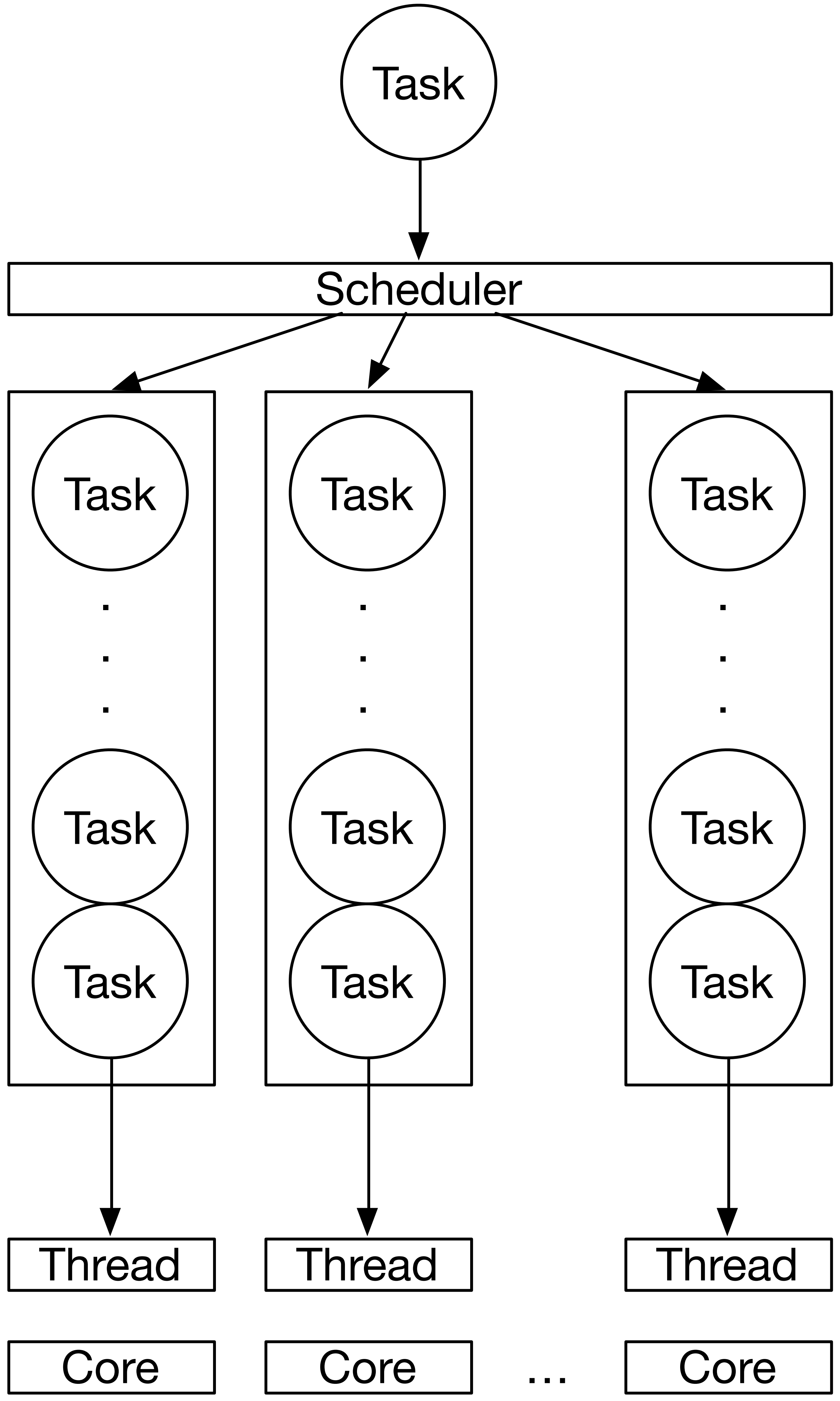
Why No Raw Synchronization Primitives?



Building a Task System



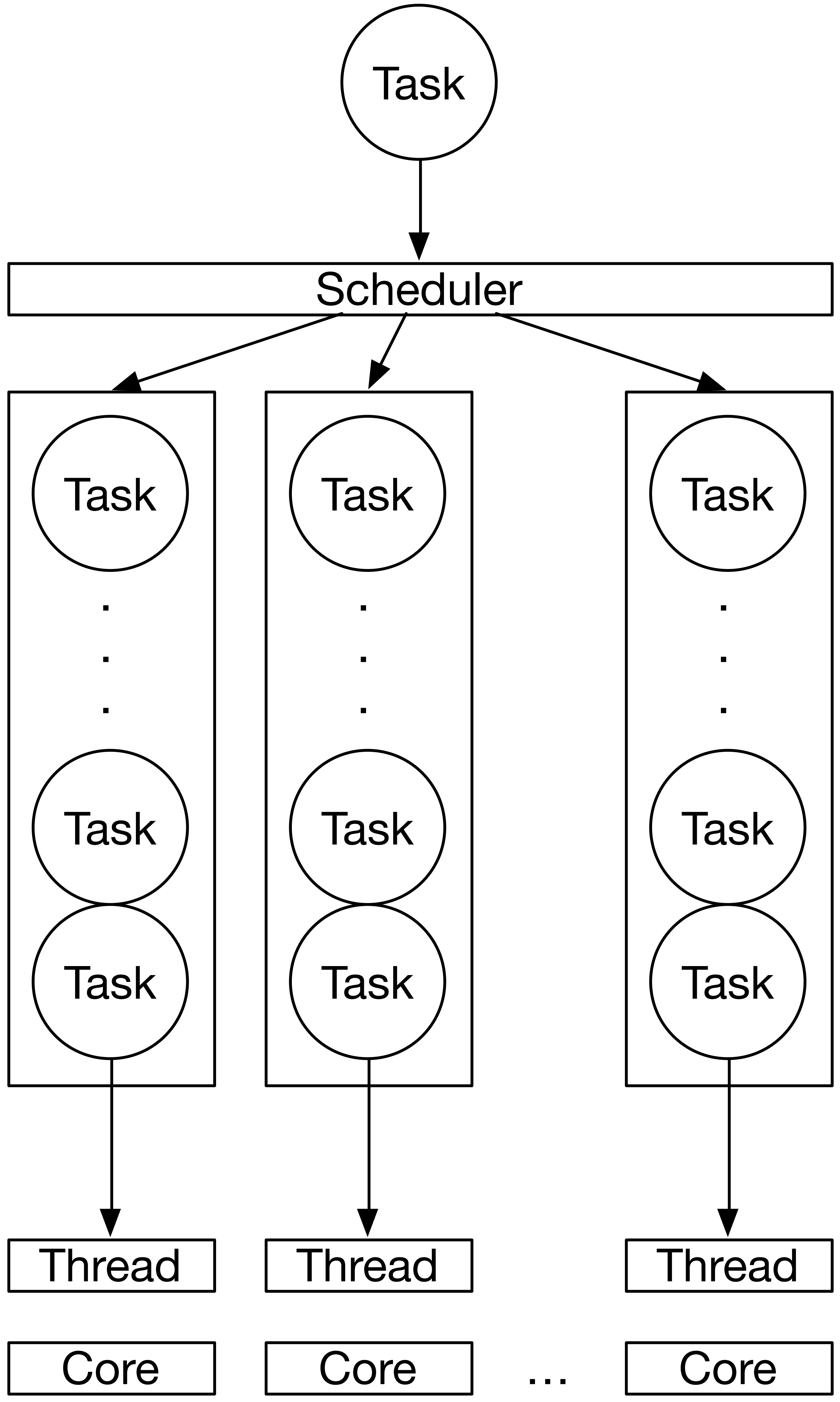
Building a Task System



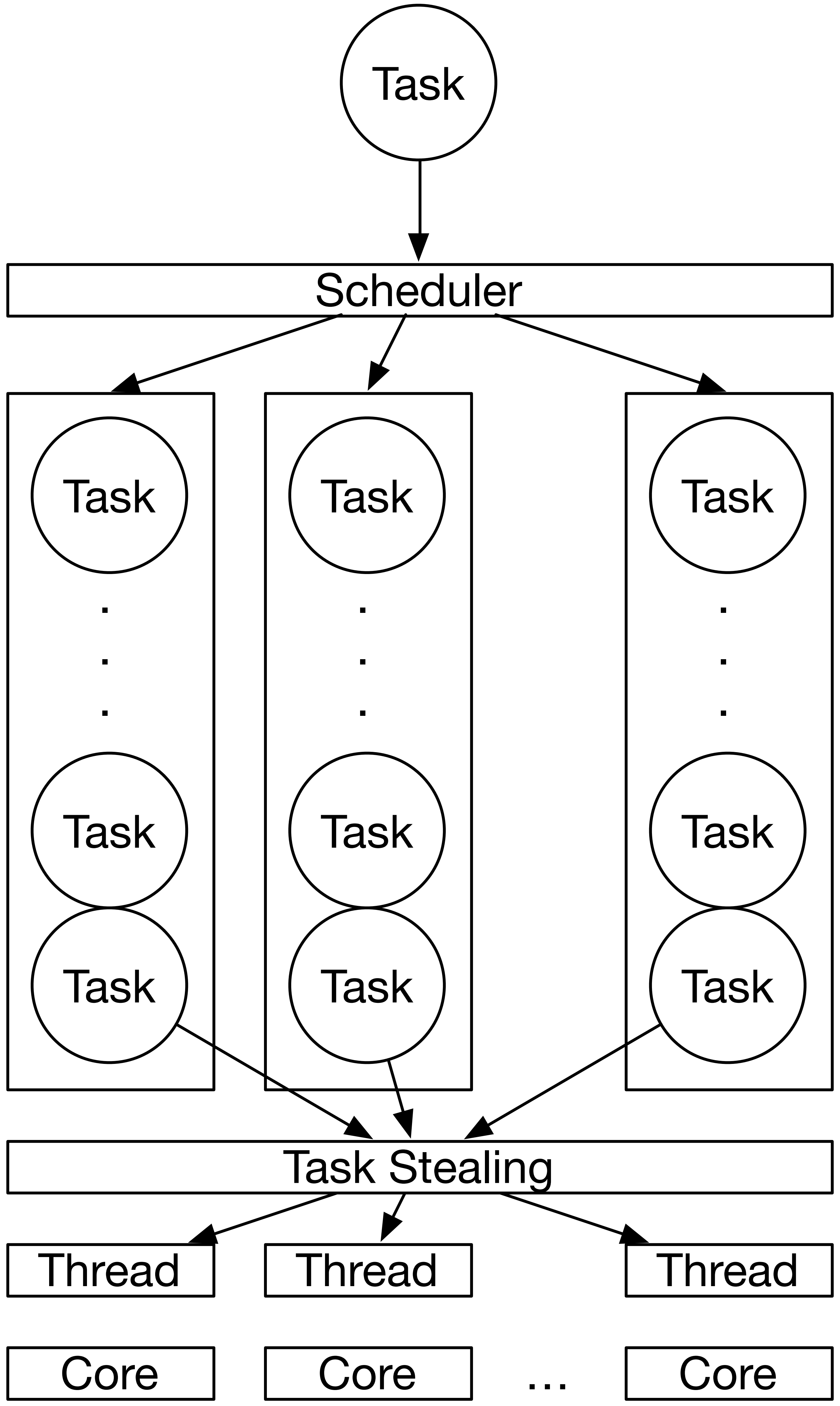
Building a Task System

```
class task_system {
    const unsigned                  _count{thread::hardware_concurrency()};
    vector<thread>                  _threads;
    vector<notification_queue>      _q{_count};
    atomic<unsigned>                _index{0};

 void run(unsigned i) {
        while (true) {
            function<void()> f;
            if (!_q[i].pop(f)) break;
            f();
        }
    }

  public:
    task_system() {…}

    ~task_system() {
        for (auto& e : _q) e.done();
        for (auto& e : _threads) e.join();
    }

    template <typename F>
    void async_(F&& f) {
        auto i = _index++;
        _q[i % _count].push(forward<F>(f));
    }
};
```

Building a Task System



Building a Task System



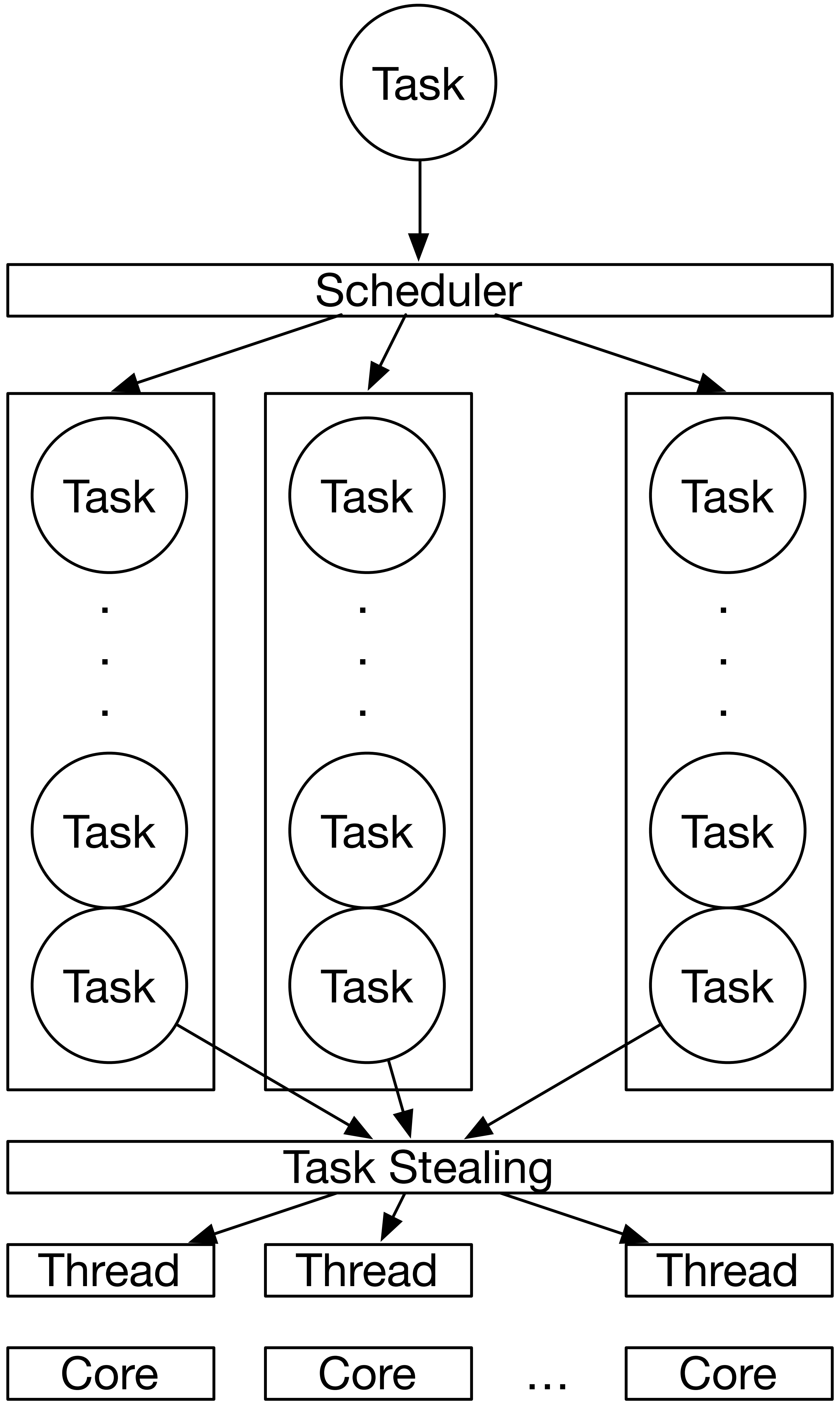
Building a Task System

```
class notification_queue {
    deque<function<void()>> _q;
    bool                    _done{false};
    mutex                   _mutex;
    condition_variable      _ready;

  public:
    bool try_pop(function<void()>& x) {
        lock_t lock{_mutex, try_to_lock};
        if (!lock || _q.empty()) return false;
        x = move(_q.front());
        _q.pop_front();
        return true;
    }

    template<typename F>
    bool try_push(F&& f) {
        {
            lock_t lock{_mutex, try_to_lock};
            if (!lock) return false;
            _q.emplace_back(forward<F>(f));
        }
        _ready.notify_one();
        return true;
    }

    void done() {
        {
            unique_lock<mutex> lock{_mutex};
```

Building a Task System

```
    void run(unsigned i) {
        while (true) {
            function<void()> f;

            for (unsigned n = 0; n != _count; ++n) {
                if (_q[(i + n) % _count].try_pop(f)) break;
            }
            if (!f && !_q[i].pop(f)) break;

            f();
        }
    }

  public:
    task_system() { … }

    ~task_system() { … }

    template <typename F>
    void async_(F&& f) {
        auto i = _index++;

        for (unsigned n = 0; n != _count; ++n) {
            if (_q[(i + n) % _count].try_push(forward<F>(f))) return;
        }

        _q[i % _count].push(forward<F>(f));
    }
};
```

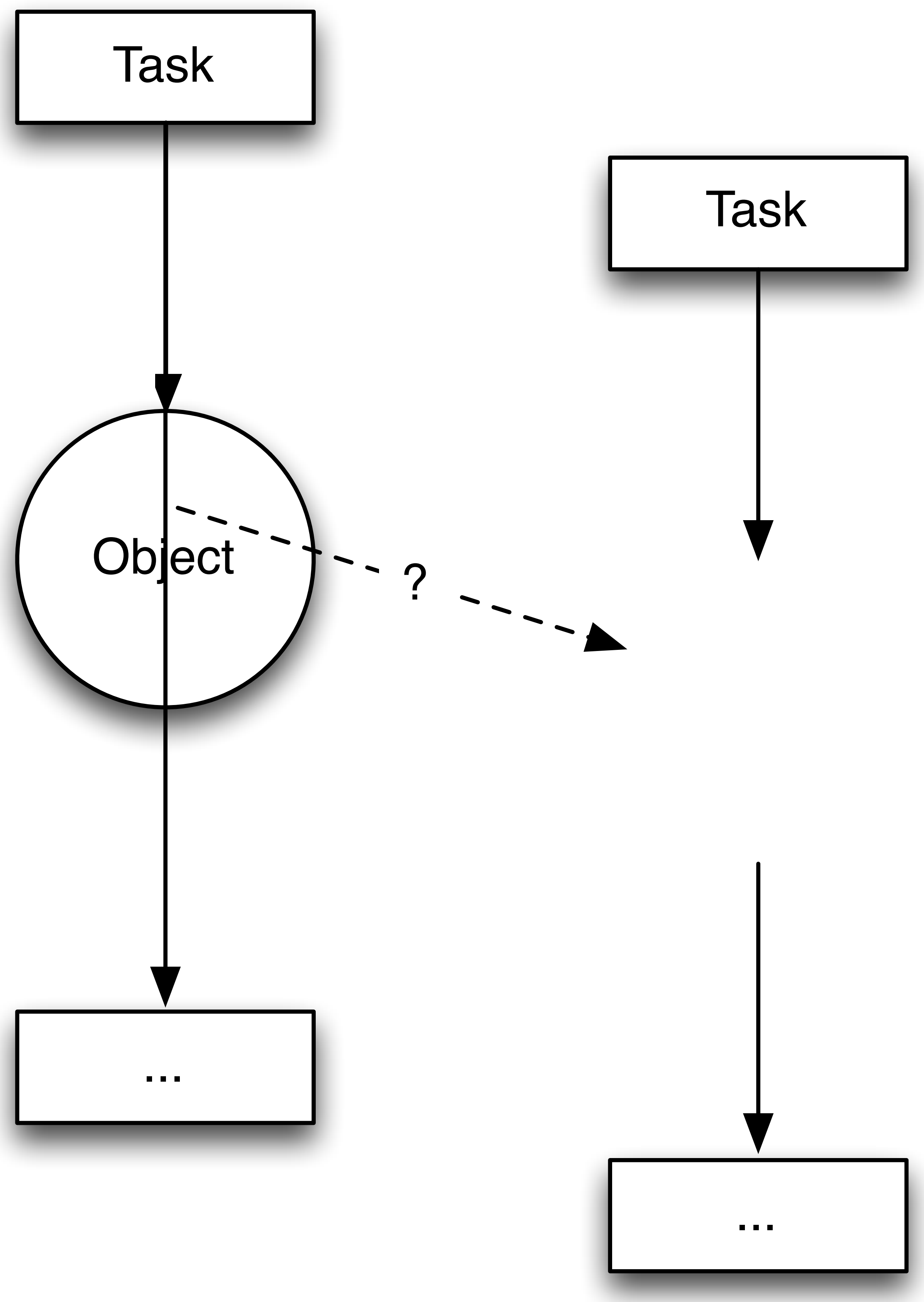
Building a Task System



Task System

- Within a few percentage points of Apple's GCD (libdispatch) under load
  - Can be improved by spinning more on try_pop in run

No Raw Synchronization Primitives



Futures

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(1'000'000); });
// Do Something
cout << x.get() << endl;
```

- Fibonacci is often used as an example for parallel algorithms
  - Please stop…

Public Service Announcement - How to Write Fibonacci

```
template <typename T, typename N, typename O>
T power(T x, N n, O op)
{
    if (n == 0) return identity_element(op);

    while ((n & 1) == 0) {
        n >>= 1;
        x = op(x, x);
    }

    T result = x;
    n >>= 1;
    while (n != 0) {
        x = op(x, x);
        if ((n & 1) != 0) result = op(result, x);
        n >>= 1;
    }
    return result;
}
```

Egyptian Multiplication (Russian Peasant Algorithm)
See “From Mathematics to Generic Programming” - Alex Stepanov and Dan Rose

Public Service Announcement - How to Write Fibonacci

```
template <typename N>
struct multiply_2x2 {
    array<N, 4> operator()(const array<N, 4>& x, const array<N, 4>& y)
    {
        return { x[0] * y[0] + x[1] * y[2], x[0] * y[1] + x[1] * y[3],
                 x[2] * y[0] + x[3] * y[2], x[2] * y[1] + x[3] * y[3] };
    }
};

template <typename N>
array<N, 4> identity_element(const multiply_2x2<N>&) { return { N(1), N(0), N(0), N(1) }; }

template <typename R, typename N>
R fibonacci(N n) {
    if (n == 0) return R(0);
    return power(array<R, 4>{ 1, 1, 1, 0 }, N(n - 1), multiply_2x2<R>())[0];
}
```

Futures

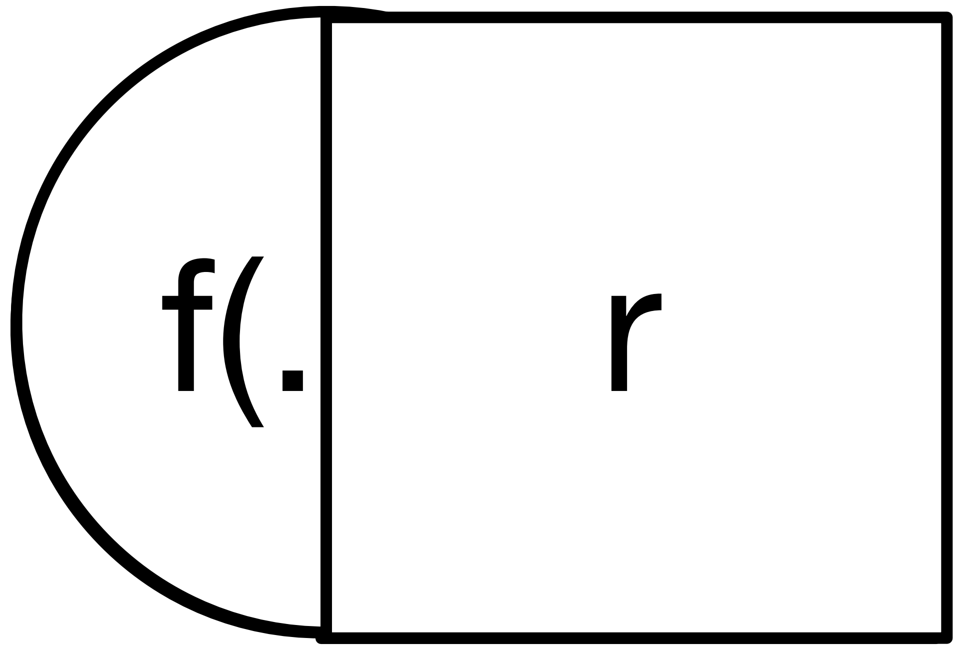
1953282128707757731632014947596256332443542996591873396953405194571625257887015694766641987634150146128795
2433522023608462551091201956023374401543811519663615691996212564289430337011382780063800276741152792746669
8655783793188228320612714975832303348548934895725992307229129019282092643316275217308614600179125820426996 5
9936020959339202005184862028402447343139811367418720203868480175318538621112878108240617741383293554561 6876
0645406512595471802912654794289403698165920636101935929135213541037679908294032015570271611539503197597 3247
7821629576316296533566947776632850623452455934606475750259358134434578167676462587885901137272990737294 7851
1448089572456191503507025589529116868550008802013233458747217794781447546792016090170642585629359747546 5327
5757574007743203491342878518979535430473456030776507893876728653916679923281744936199152376814955763208 5371
0478597061884387315305823956275608790631078190049751695947097367138917457045552021351233507944033607120 3050
4144685221041565037321067932275625864751191461141736034968121738023422478608029202109319249649040983239 7066
8324705444176351252673245527541950168384520602300739495985427929829783120438211575764578769249558335140 2522
1527206624418090032593807536284917966809529711850719137983367887377045991363933395581421203699026161797 2113
2509184002305532760710431647819097430043464779336328760146999612802392582947155731668894333945542929287 1877
4877478920429616635653661079602391970210972847296670942733458634479804863394463521165497150726134276820 5479
3209317507988801013041602798250635418234403455874223670128266635693461129461312312838906003654732766024 5693
1515185001832848315064548002997893598516123707404615822935444070174833951457586954749175026454212636426 2224
7206004885546258996119047589210122428054289862159464666247856437357221777554987608768591203011855163566 8902
0103446399839773266388890365078416180709154525299275973552139574154777291460087943143391560604458251078 23511
6627189263792331301464388059787946844487906057678629746089896274266635696824742933867402074365594260579447 90
7119305225893159071938654552588042913974714018184916973383813844615484306312364929083558427807845613193 6457
5591172213694633818031160030789621166865289595377843646440238251636244971819738544414956313171400285033 8928
2227413460301809422483721632185471727045281382407842563874736524914111808078386650633994537623920670051 3391
8733310713606969818962828476324542329930627287045799129324574116753390227449996309656668092226251646858 2544
5578513498241441272612401581575381809846666714500698883917855180089437018902572199248520874291556026191 7752
2812466062899678716652967848726848490504132849729771268801163997837643428020245225155010224035416988518 5375
0158467388119404761972061960312653449675991789324447817070290444658957195022880915779389764242375181402 0998
9995816123147790229578110016867018673861986179713813985466628196954855374070735622861616553942807641840 8092
1204793281668300598450478792940635631809747975515203509468276591874161090763750690276529436756153980326 1388
901944859410045292275418809457356207954218996629634413463969559809913750100537602594401136172191768811472 64

0.72s to calculate
208,988 digits

Futures

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(1'000'000); });

// Do Something

cout << x.get() << endl;
```

Futures



Futures

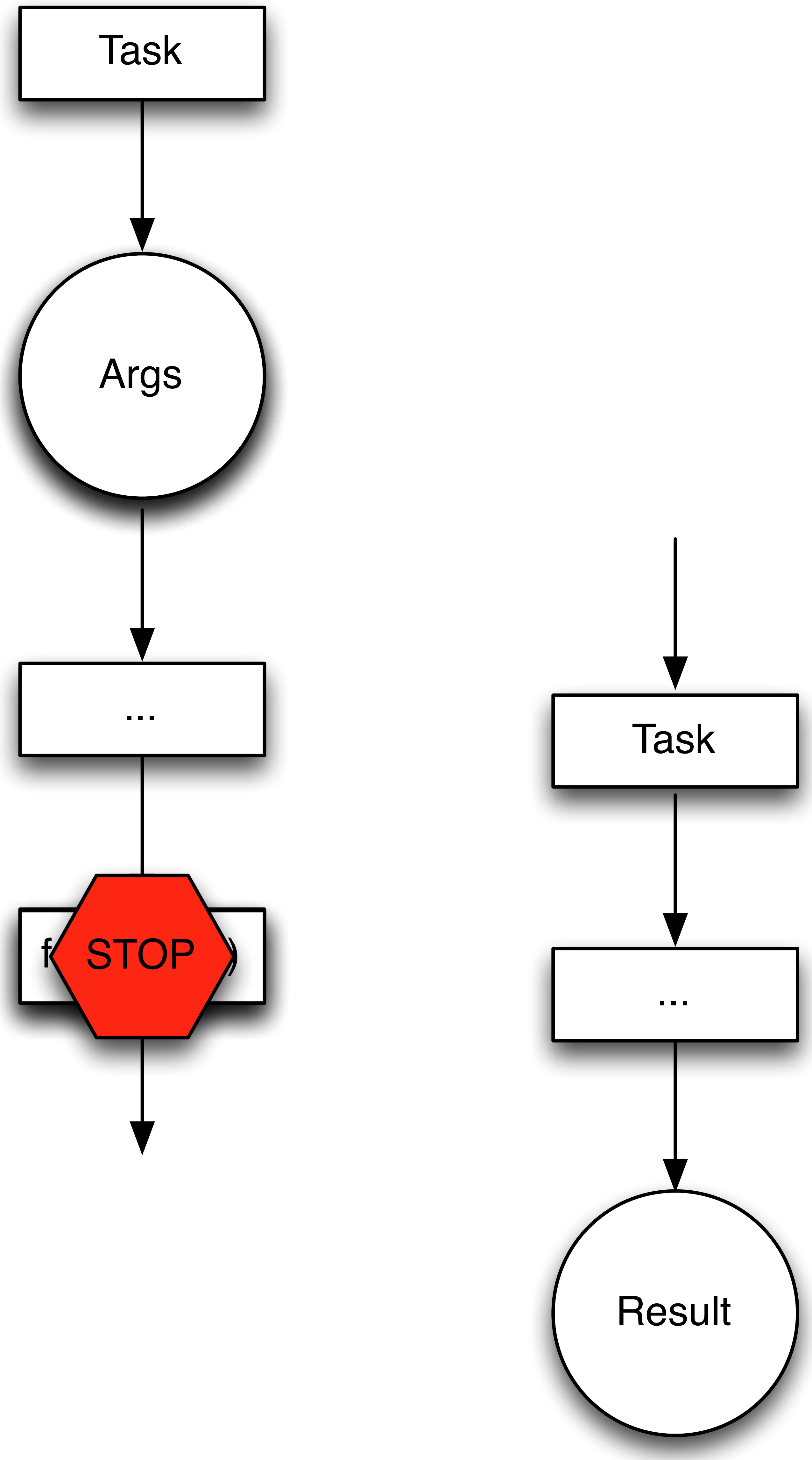
- Futures allow minimal code transformations to express dependencies

Exception Marshalling

```
future<cpp_int> x = async([]{
    throw runtime_error("failure");
    return fibonacci<cpp_int>(1'000'000);
});

// Do Something

try {
    cout << x.get() << endl;
} catch (const runtime_error& error) {
    cout << error.what() << endl;
}
```

```
failure
```

No Raw Synchronization Primitives

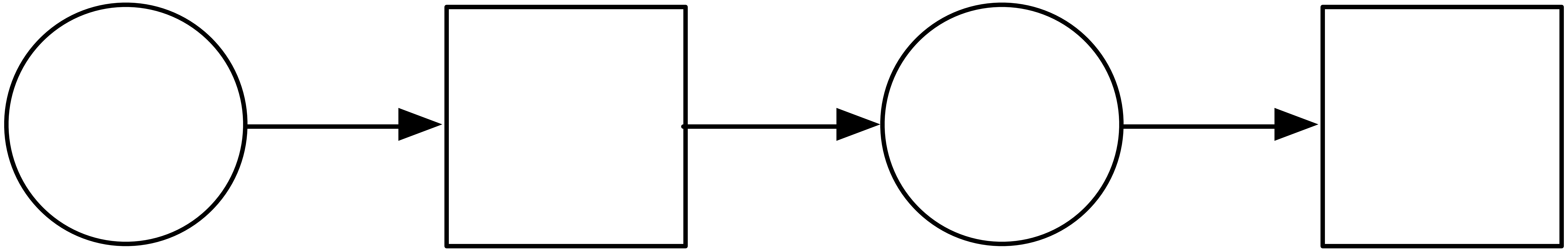


Futures: What year is this?

- C++14 futures lack:
  - Continuations - `.then()`
  - Joins - `when_all()`
  - Split
  - Cancelation
  - Progress Monitoring (Except Ready)

  - And C++14 futures don't compose (easily) to add these features

Futures: Continuations



Futures: Continuations

- Blocking on `std::future.get()` has two problems
  - One thread resource is consumed, increasing contention
    - Possibly causing a deadlock in our tasking system!
  - Any subsequent non-dependent calculations on the task are also blocked

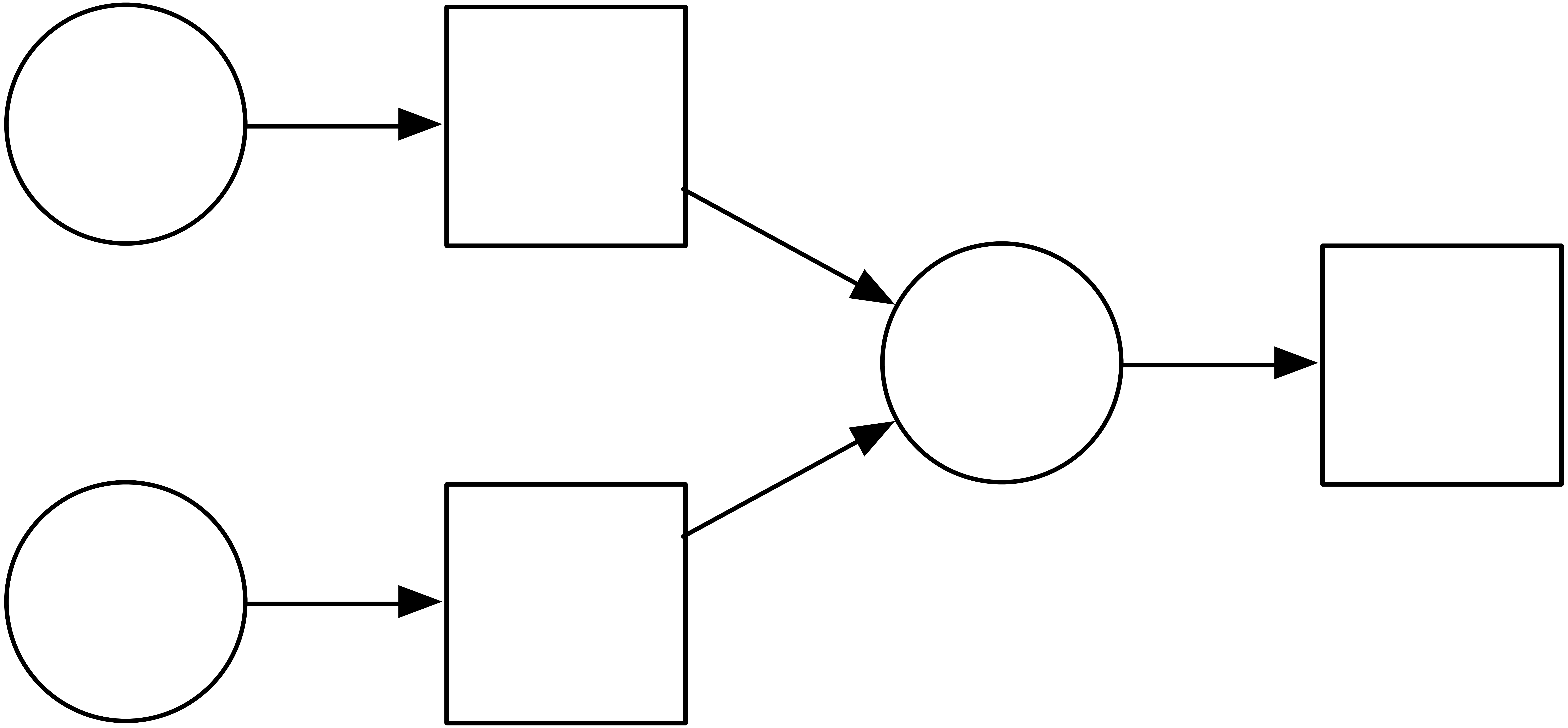
- C++14 doesn’t have continuations
  - GCD has serialized queues and groups
  - PPL has chained tasks
  - TBB has flow graphs
  - TS Concurrency will have `.then()`
    - Boost futures have them now

Futures: Continuations

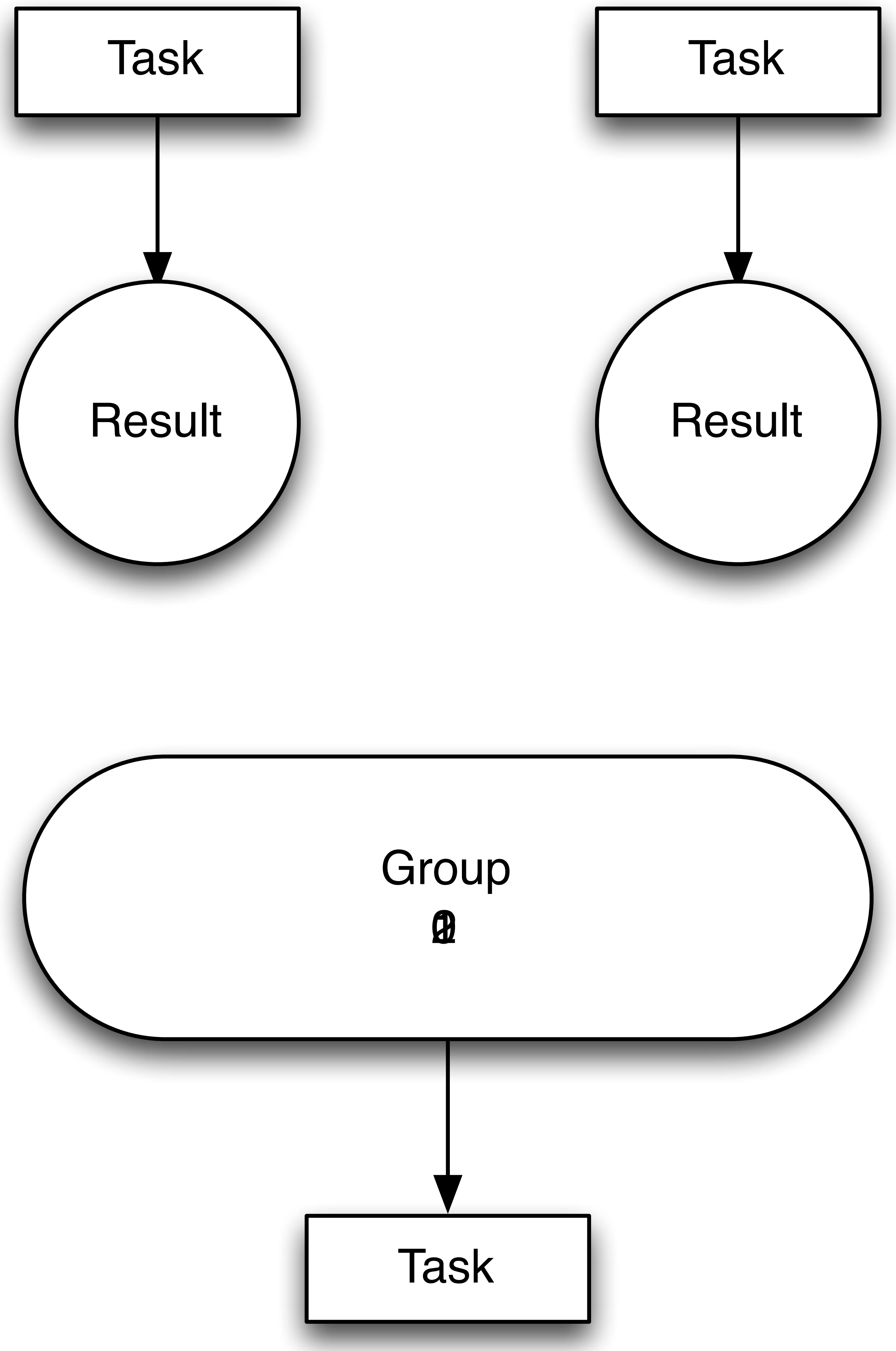
```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(1'000); });

future<void> y = x.then([](future<cpp_int> x){ cout << x.get() << endl; });

// Do something

y.wait();
```

```
43466557686937456435688527675040625802564660517371780402481729089536555417949051890403879840079255169295922593080322634775209
689623239873322471161642996440906533187938298969649928516003704476137795166849228875
```

Futures: Joins



Task Systems



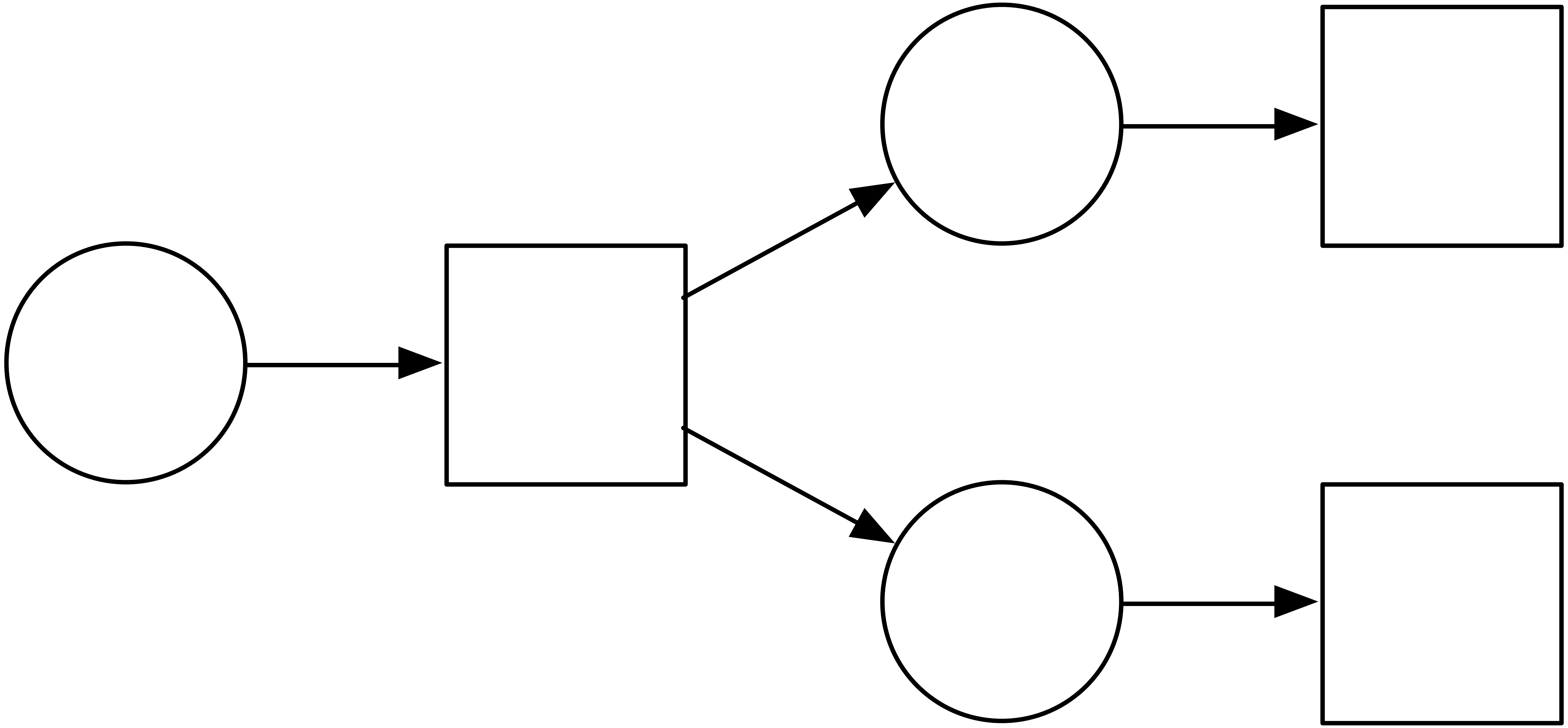
Futures: Continuations

```
auto x = async([]{ return fibonacci<cpp_int>(1'000'000); });
auto y = async([]{ return fibonacci<cpp_int>(2'000'000); });

auto z = when_all(std::move(x), std::move(y)).then([](auto f){
    auto t = f.get();
    return cpp_int(get<0>(t).get() * get<1>(t).get());
});

cout << z.get() << endl;
```

f is a future tuple of futures

result is 626,964 digits

Futures: Split



Futures: Continuations

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(100); });

future<cpp_int> y = x.then([](future<cpp_int> x){ return cpp_int(x.get() * 2); });
future<cpp_int> z = x.then([](future<cpp_int> x){ return cpp_int(x.get() / 15); });
```

Thread 1: signal SIGABRT

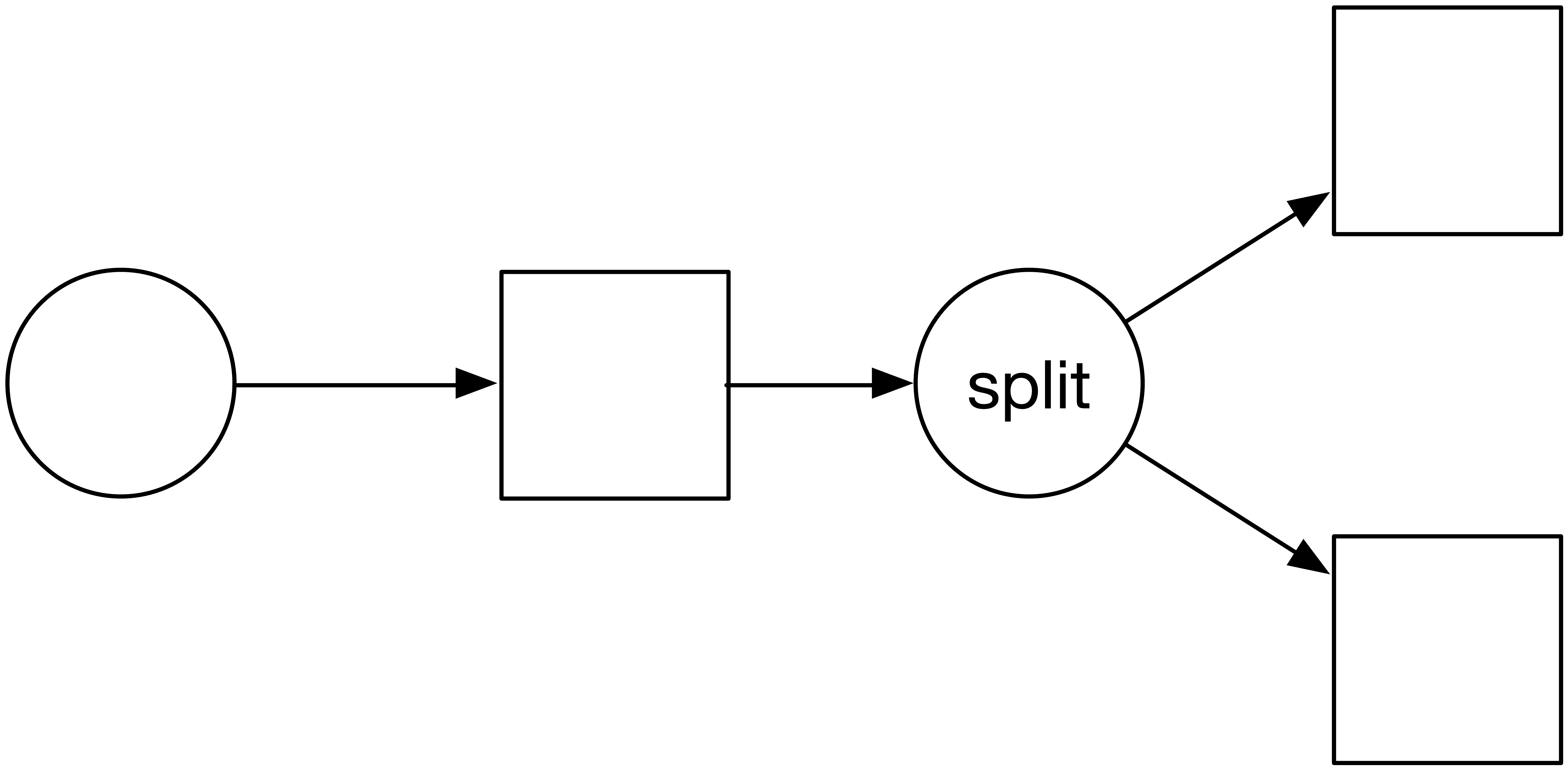
```
Assertion failed: (px != 0), function operator->, file shared_ptr.hpp, line 648.
```

Continuations

- Desired behavior
  - A future should behave as a *regular* type - a token for the actual value
    - shared_futures let me pass “copy” them around and do multiple get() operations
      - But not multiple continuations

Continuations

- We can write a pseudo-copy, split().



Futures: Continuations

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(100); });

future<cpp_int> y = split(x).then([](future<cpp_int> x){ return cpp_int(x.get() * 2); });
future<cpp_int> z = x.then([](future<cpp_int> x){ return cpp_int(x.get() / 15); });

future<void> done = when_all(std::move(y), std::move(z)).then([](auto f){
    auto t = f.get();
    cout << get<0>(t).get() << endl;
    cout << get<1>(t).get() << endl;
});

done.wait();
```

```
708449696358523830150
23614989878617461005
```

Building Blocks

- Promise is the sending side of a future
- Promises are packaged with a function to formed a packaged task
  - Packaged tasks handle the exception marshalling through a promise

Promise

```
promise<int> x;
future<int> y = x.get_future();

x.set_value(42);
cout << y.get() << endl;
```

42

Futures: Split

```
template <typename T>
auto split(future<T>& x) {

    auto tmp = std::move(x);

    promise<T> p;
    x = p.get_future(); // replace x with new future

    return tmp.then([_p = move(p)](auto _tmp) mutable {
        auto value = _tmp.get();
        _p.set_value(value); // assign to new "x" future
        return value; // return value through future result
    });
}
```

Futures: Split

```
template <typename T>
auto split(future<T>& x) {

    auto tmp = std::move(x);

    promise<T> p;
    x = p.get_future(); // replace x with new future

    return tmp.then([_p = std::move(p)](auto _tmp) mutable {
        if (_tmp.has_exception()) {
            auto error = _tmp.get_exception_ptr();
            _p.set_exception(error);
            rethrow_exception(error);
        }

        auto value = _tmp.get();
        _p.set_value(value); // assign to new "x" future
        return value; // return value through future result
    });
}
```

Futures: Continuations

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(100); });

future<cpp_int> y = split(x).then([](future<cpp_int> x){ return cpp_int(x.get() * 2); });
future<cpp_int> z = x.then([](future<cpp_int> x){ return cpp_int(x.get() / 15); });

future<void> done = when_all(std::move(y), std::move(z)).then([](auto f){
    auto t = f.get();
    cout << get<0>(t).get() << endl;
    cout << get<1>(t).get() << endl;
});

done.wait();
```

```
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23614989878617461005
```
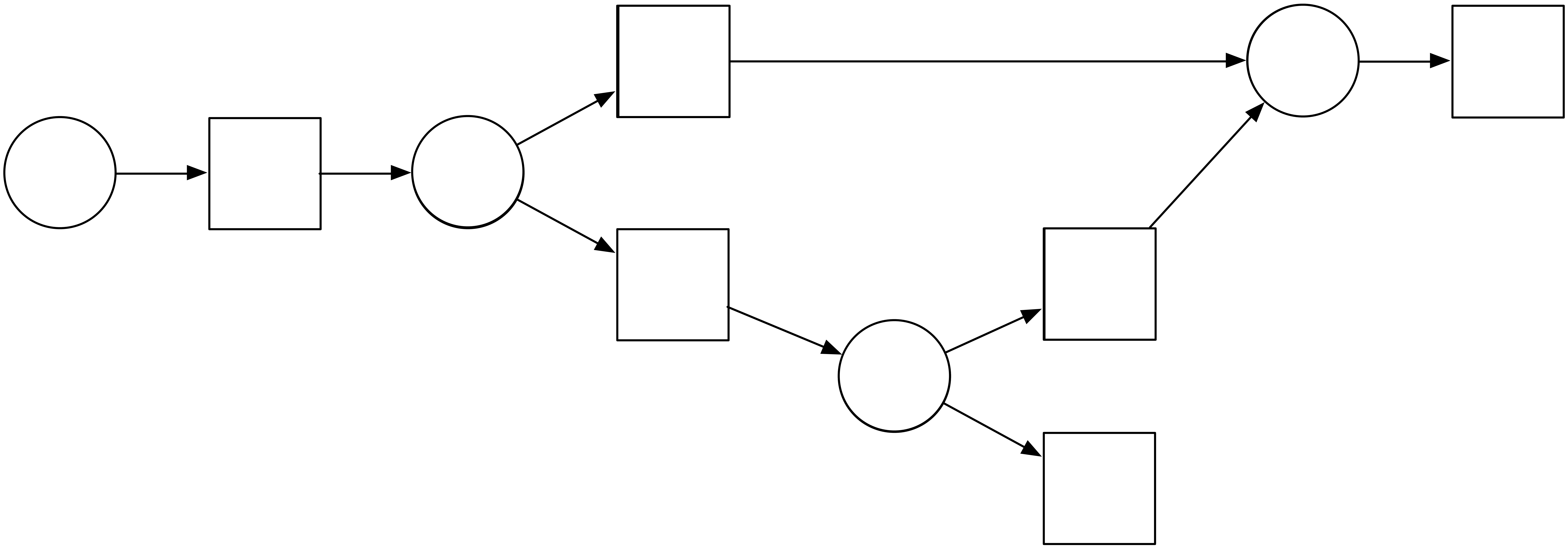

Cancelation

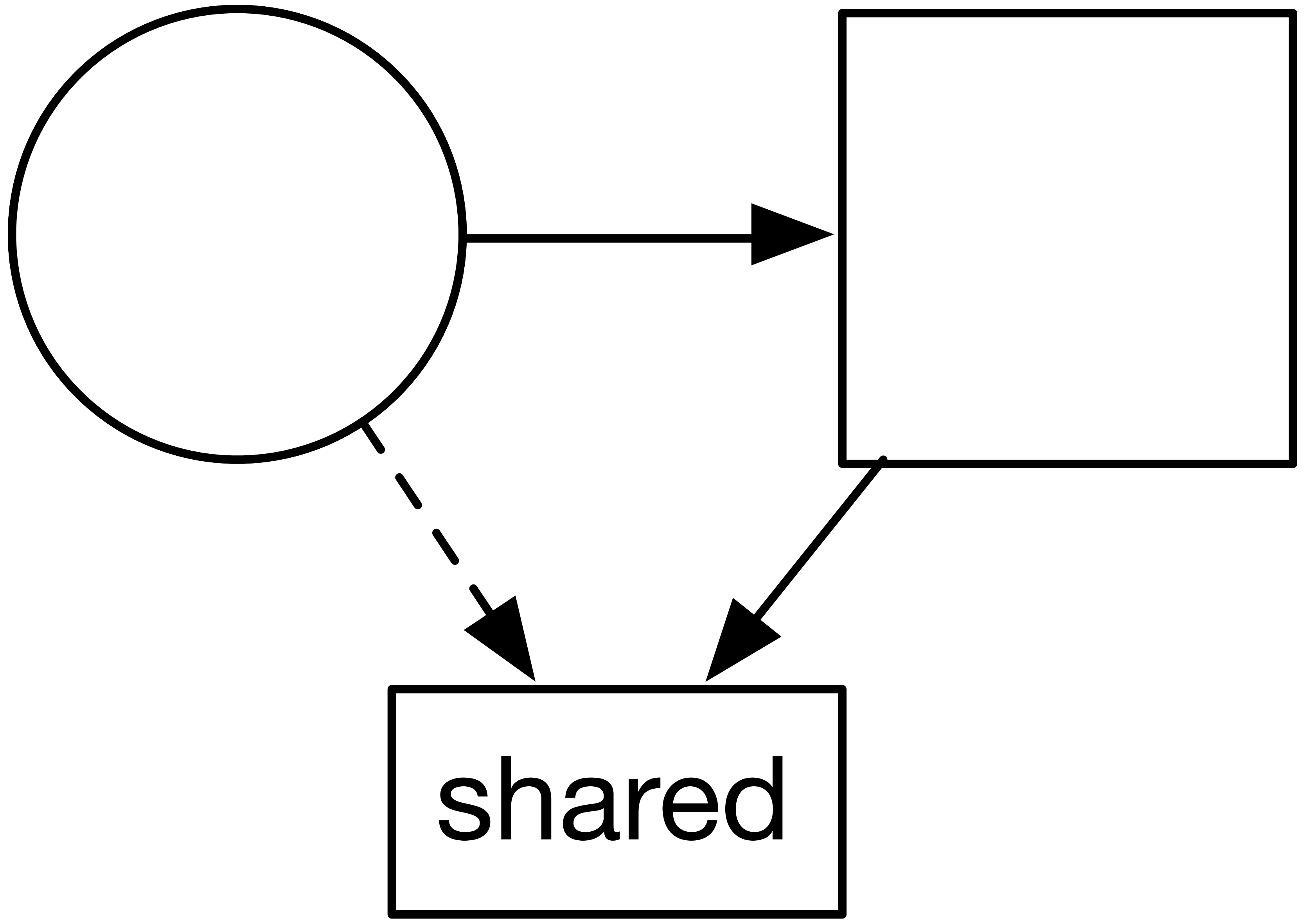
- When the (last) future destructs
  - The associated task that has not started, should not execute (NOP)
  - The resource held by that task should be released
    - Since that task may hold futures for other tasks, the system unravels

- I do not know of a good way to compose such cancelation with current futures
  - Except to create something more complex than re-implementing futures

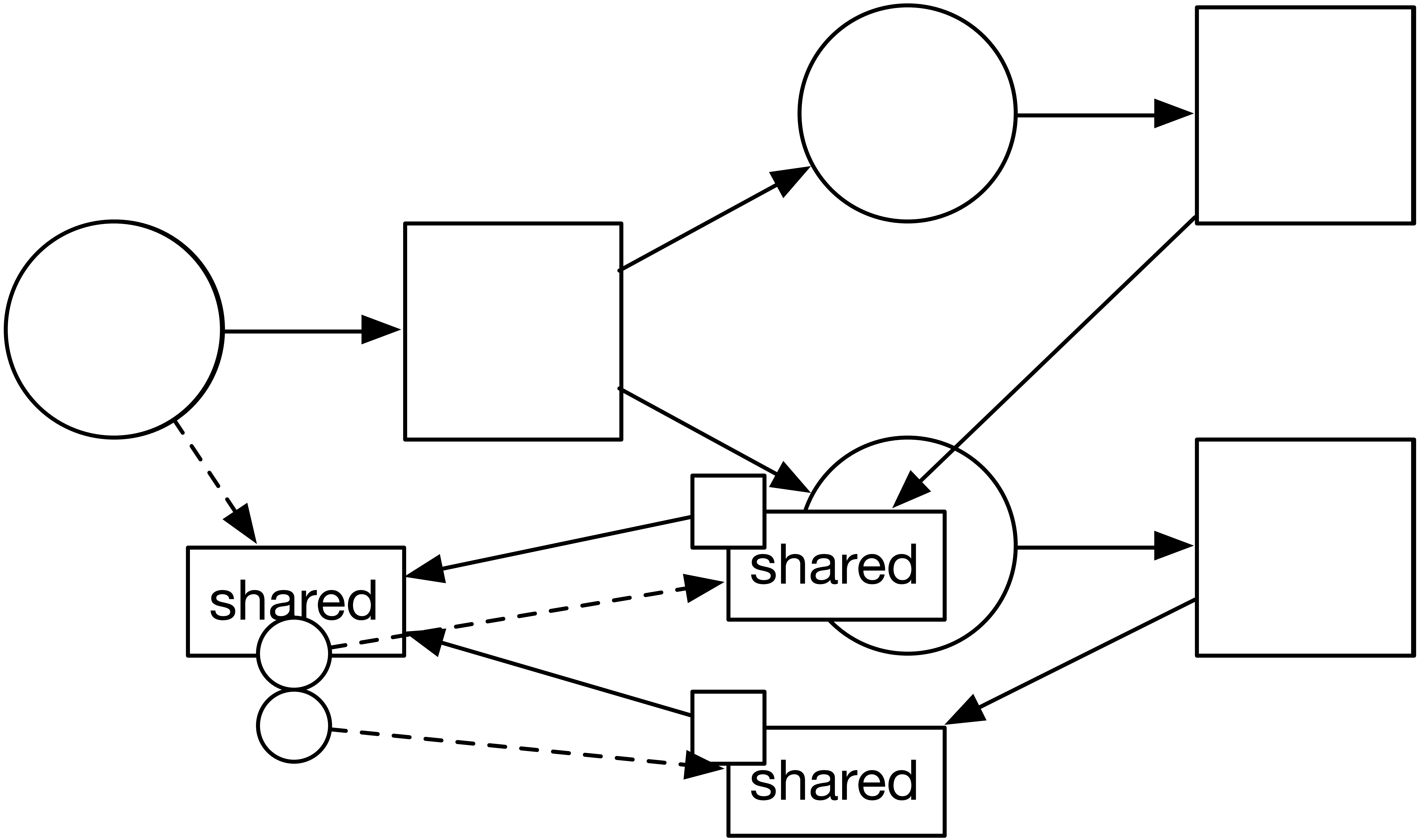
Cancelation



Futures



Futures



Futures: Building, The

```
template <typename>
struct result_of_; //not defined

template <typename R, typename... Args>
struct result_of_<R(Args...)> { using type = R; };

template <typename F>
using result_of_t_ = typename result_of_<F>::type;
```

result_of_t_<int(double)> -> int

Futures: Building, The

```
template <typename> class packaged_task; //not defined

template <typename R>
class future {
    shared_ptr</* ... */> _p;

 public:
    future() = default;

    template <typename F>
    auto then(F&& f) { }

    const R& get() const { }
};

template<typename R, typename ...Args >
class packaged_task<R (Args...)> {
    weak_ptr</* ... */> _p;

 public:
    packaged_task() = default;

    template <typename... A>
    void operator()(A&&... args) const { }
};
```

Futures: Building, The

```
template <typename> class packaged_task; //not defined
template <typename> class future;

template <typename S, typename F>
auto package(F&& f) -> pair<packaged_task<S>, future<result_of_t_<S>>>;

template <typename R>
class future {
    shared_ptr</* ... */> _p;

    template <typename S, typename F>
    friend auto package(F&& f) -> pair<packaged_task<S>, future<result_of_t_<S>>>;

    explicit future(shared_ptr</* ... */> p) : _p(move(p)) { }
    /* ... */
};

template<typename R, typename ...Args >
class packaged_task<R (Args...)> {
    weak_ptr</* ... */> _p;

    template <typename S, typename F>
    friend auto package(F&& f) -> pair<packaged_task<S>, future<result_of_t_<S>>>;

    explicit packaged_task(weak_ptr</* ... */> p) : _p(move(p)) { }
    /* ... */
};
```

Futures: Building, The

```
template <typename S, typename F>
auto package(F&& f) -> pair<packaged_task<S>, future<result_of_t_<S>>> {
    auto p = make_shared<shared<S>>(forward<F>(f));
    return make_pair(packaged_task<S>(p), future<result_of_t_<S>>(p));
}
```

```
package<int(double)>(f) -> { void(double), future<int> }
```

Futures: Building, The

```
template <typename R>
struct shared_base {
    vector<R> _r; // optional
    mutex _mutex;
    condition_variable _ready;
    vector<function<void()>> _then;

    virtual ~shared_base() { }

    /* ... */
};
```

```
template <typename> struct shared; // not defined

template <typename R, typename... Args>
struct shared<R(Args...)> : shared_base<R> {
    function<R(Args...)> _f;

    template<typename F>
    shared(F&& f) : _f(forward<F>(f)) { }

    /* ... */
};
```

Futures: Building, The

```
template<typename R, typename ...Args >
class packaged_task<R (Args...)> {
    weak_ptr<shared<R(Args...)>> _p;

    template <typename S, typename F>
    friend auto package(F&& f) -> pair<packaged_task<S>, future<result_of_t_<S>>>;

    explicit packaged_task(weak_ptr<shared<R(Args...)>> p) : _p(move(p)) { }

 public:
    packaged_task() = default;

    template <typename... A>
    void operator()(A&&... args) const {
        auto p = _p.lock();
        if (p) (*p)(forward<A>(args)...);
    }
};
```

Futures: Building, The

```
template <typename R, typename... Args>
struct shared<R(Args...)> : shared_base<R> {
    function<R(Args...)> _f;

    template<typename F>
    shared(F&& f) : _f(forward<F>(f)) { }

    template <typename... A>
    void operator()(A&&... args) {
        this->set(_f(forward<A>(args)...));
        _f = nullptr;
    }
};
```

Futures: Building, The

```
template <typename R>
struct shared_base {
    vector<R> _r; // optional
    mutex _mutex;
    condition_variable _ready;
    vector<function<void()>> _then;

    virtual ~shared_base() { }

    void set(R&& r) {
        vector<function<void()>> then;
        {
            lock_t lock{_mutex};
            _r.push_back(move(r));
            swap(_then, then);
        }
        _ready.notify_all();
        for (const auto& f : then) _system.async_(move(f));
    }
};
```

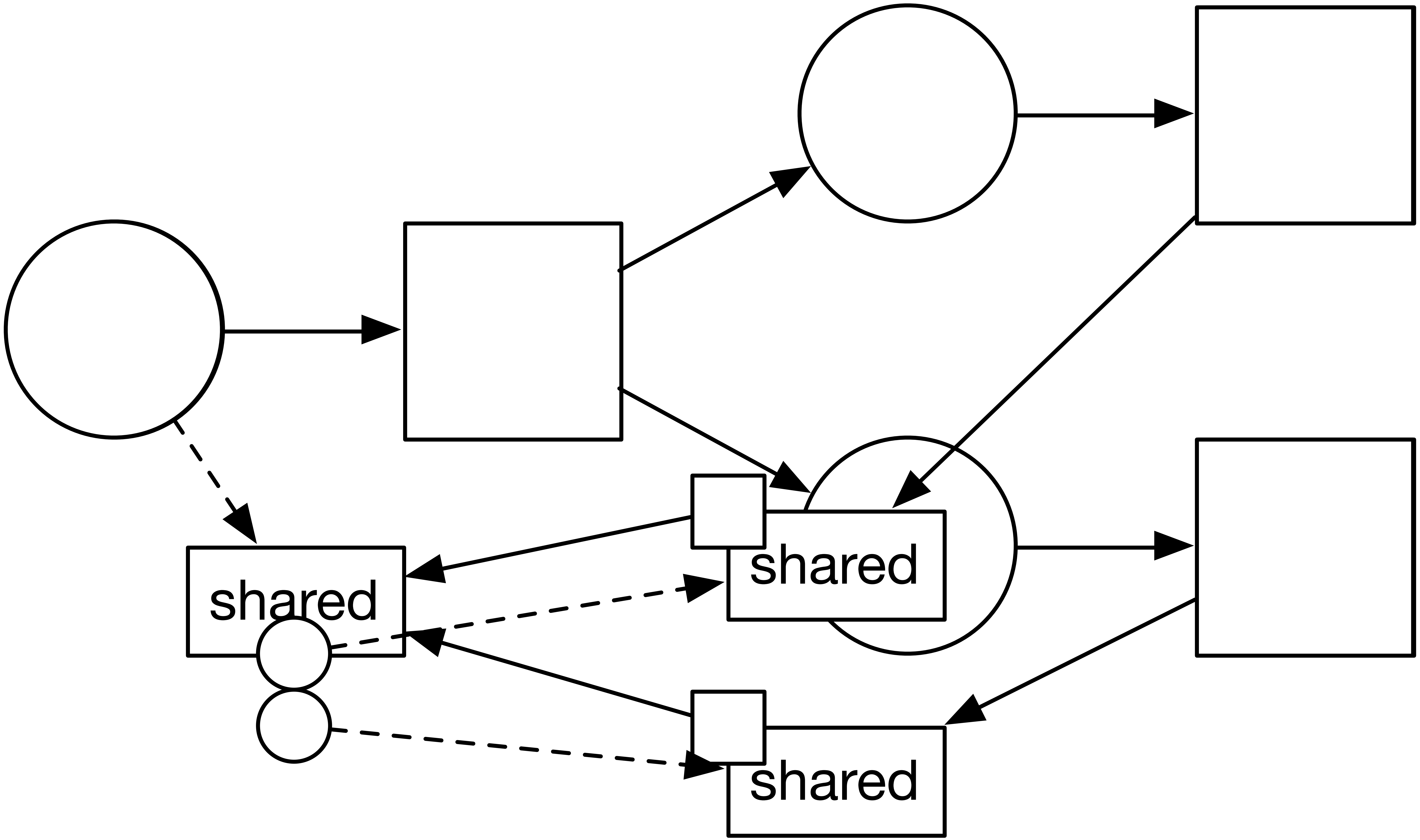
Futures: Building, The

```
template <typename R>
class future {
    shared_ptr<shared_base<R>> _p;

    template <typename S, typename F>
    friend auto package(F&& f) -> pair<packaged_task<S>, future<result_of_t_<S>>>;

    explicit future(shared_ptr<shared_base<R>> p) : _p(move(p)) { }
 public:
    future() = default;

    template <typename F>
    auto then(F&& f) {
        auto pack = package<result_of_t<F(R)>()>([p = _p, f = forward<F>(f)](){
            return f(p->_r.back());
        });
        _p->then(move(pack.first));
        return pack.second;
    }

    const R& get() const { return _p->get(); }
};
```

Futures: Building, The

```
template <typename R>
struct shared_base {
    vector<R> _r; // optional
    mutex _mutex;
    condition_variable _ready;
    vector<function<void()>> _then;

    virtual ~shared_base() { }

    void set(R&& r) {…}

    template <typename F>
    void then(F&& f) {
        bool resolved{false};
        {
            lock_t lock{_mutex};
            if (_r.empty()) _then.push_back(forward<F>(f));
            else resolved = true;
        }
        if (resolved) _system.async_(move(f));
    }

    const R& get() {
        lock_t lock{_mutex};
        while (_r.empty()) _ready.wait(lock);
        return _r.back();
    }
};
```

Futures



Futures: Building, The

```
template <typename F, typename ...Args>
auto async(F&& f, Args&&... args)
{
    using result_type = result_of_t<F (Args...)>;
    using packaged_type = packaged_task<result_type()>;

    auto pack = package<result_type()>(bind(forward<F>(f), forward<Args>(args)...));

    thread(move(get<0>(pack))).detach(); // Replace with task queue
    return get<1>(pack);
}
```

Futures: Continuations

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(100); });

future<cpp_int> y = x.then([](const cpp_int& x){ return cpp_int(x * 2); });
future<cpp_int> z = x.then([](const cpp_int& x){ return cpp_int(x / 15); });

cout << y.get() << endl;
cout << z.get() << endl;
```

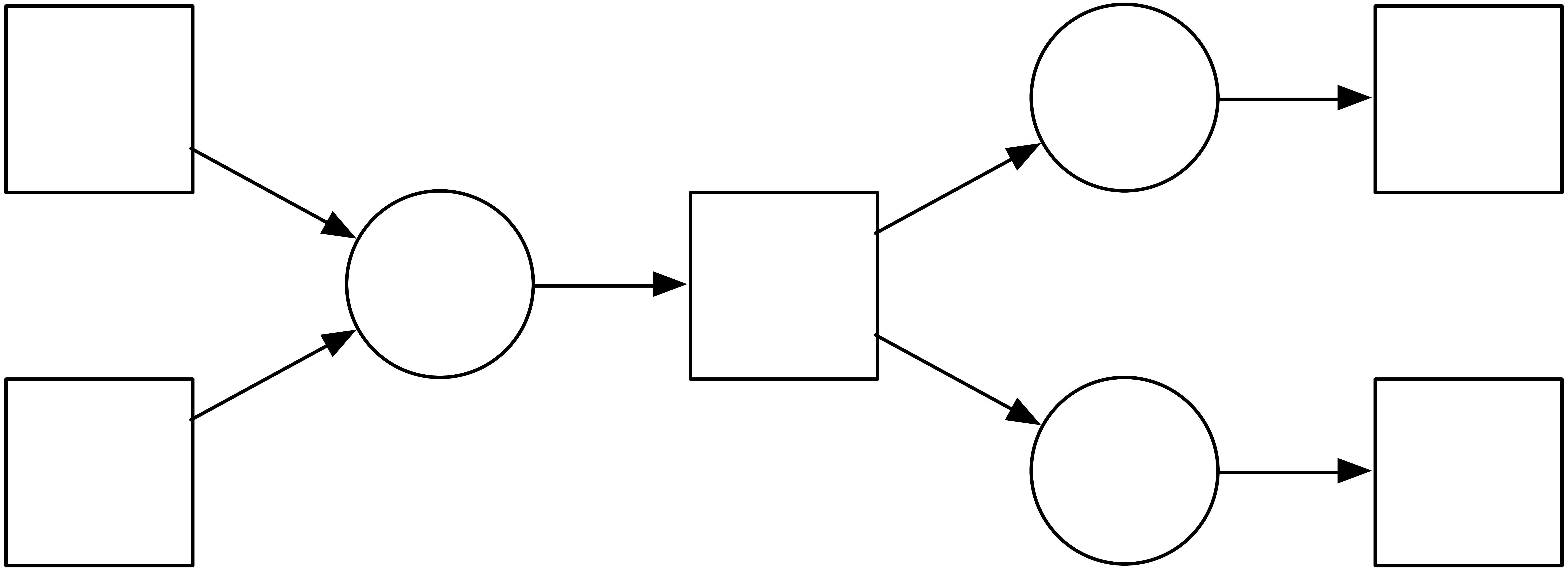
```
708449696358523830150
23614989878617461005
```

Exercises

- Add support for:
  - Join (when_all)
  - Broken promises
  - Exception marshalling
  - Progress reporting

Channels

What if we persist the graph?



What if we persist the graph?

- Allow multiple invocations of the tasks by setting the source values
- Each change triggers a notification to the sink values
  - This is a reactive programming model and futures are known as *behaviors* or *channels*

Accumulators and Generator

- Each operation does not have to be a 1:1 mapping of input to output
- Coroutines are one way to write n:m functions

```
channel<int> send;

auto hold = send
    | [](const receiver<int>& r) {
        int sum = 0;
        while(auto v = await r) {
            sum += v.get();
        }
        return sum;
    }
    | [](int x){ cout << x << '\n'; };

send(1);
send(2);
send(3);
send.close();
```

6

Futures: Continuations

```
sender<int> send;
receiver<int> receive;

tie(send, receive) = channel<int>();

auto hold = receive
    | sum()
    | [](int x){ cout << x << '\n'; };

receive.set_ready();

send(1);
send(2);
send(3);
send.close();
```

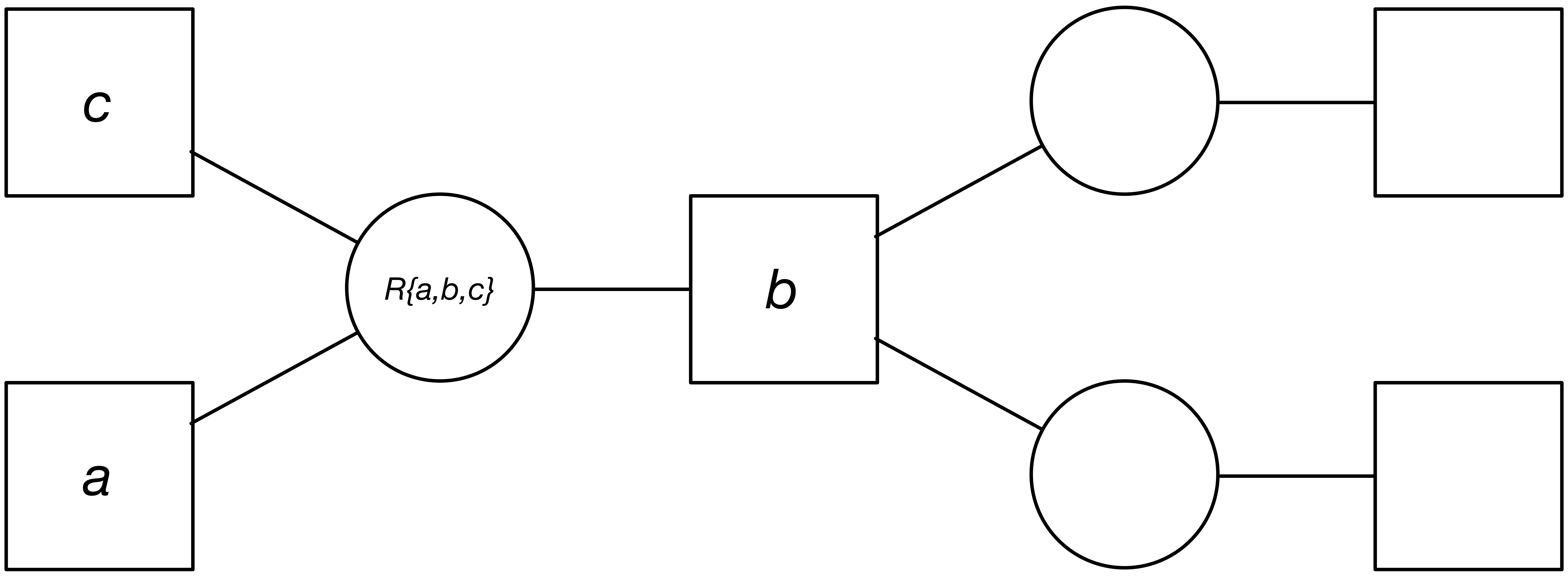
6

```
struct sum {
    process_state _state = process_state::await;
    int _sum = 0;

    void await(int n) { _sum += n; }

    int yield() { _state = process_state::await; return _sum; }

    void close() { _state = process_state::yield; }

    auto state() const { return _state; }
};
```

Property Models

How do the graphs change during execution?

Property Model

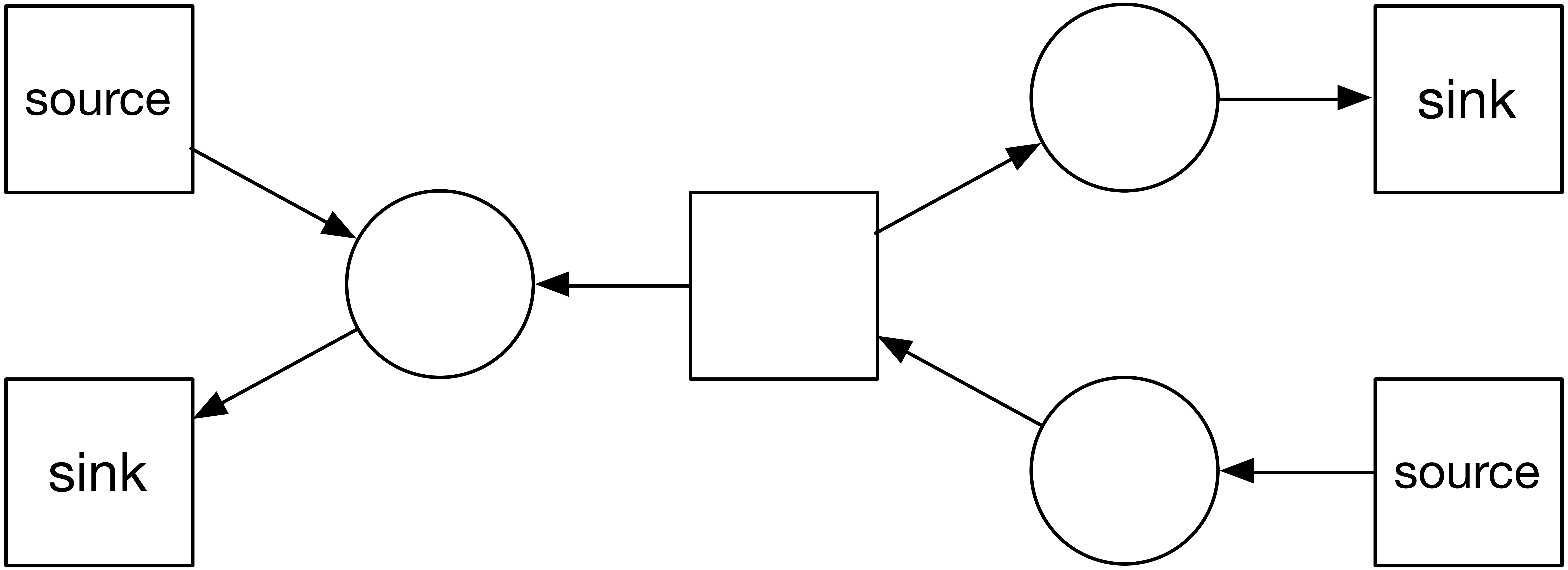


A function is a directed relationship

- We can remove the arrows by providing a package of functions to represent the relationship
  - a = b * c
    b = a / c
    c = a / b
  - This forms a type of constraint system called a *property model*
  - Flow is determined by value, or *cell*, priority

  - Cells can only have one in-edge for a given flow or the system is over constrained

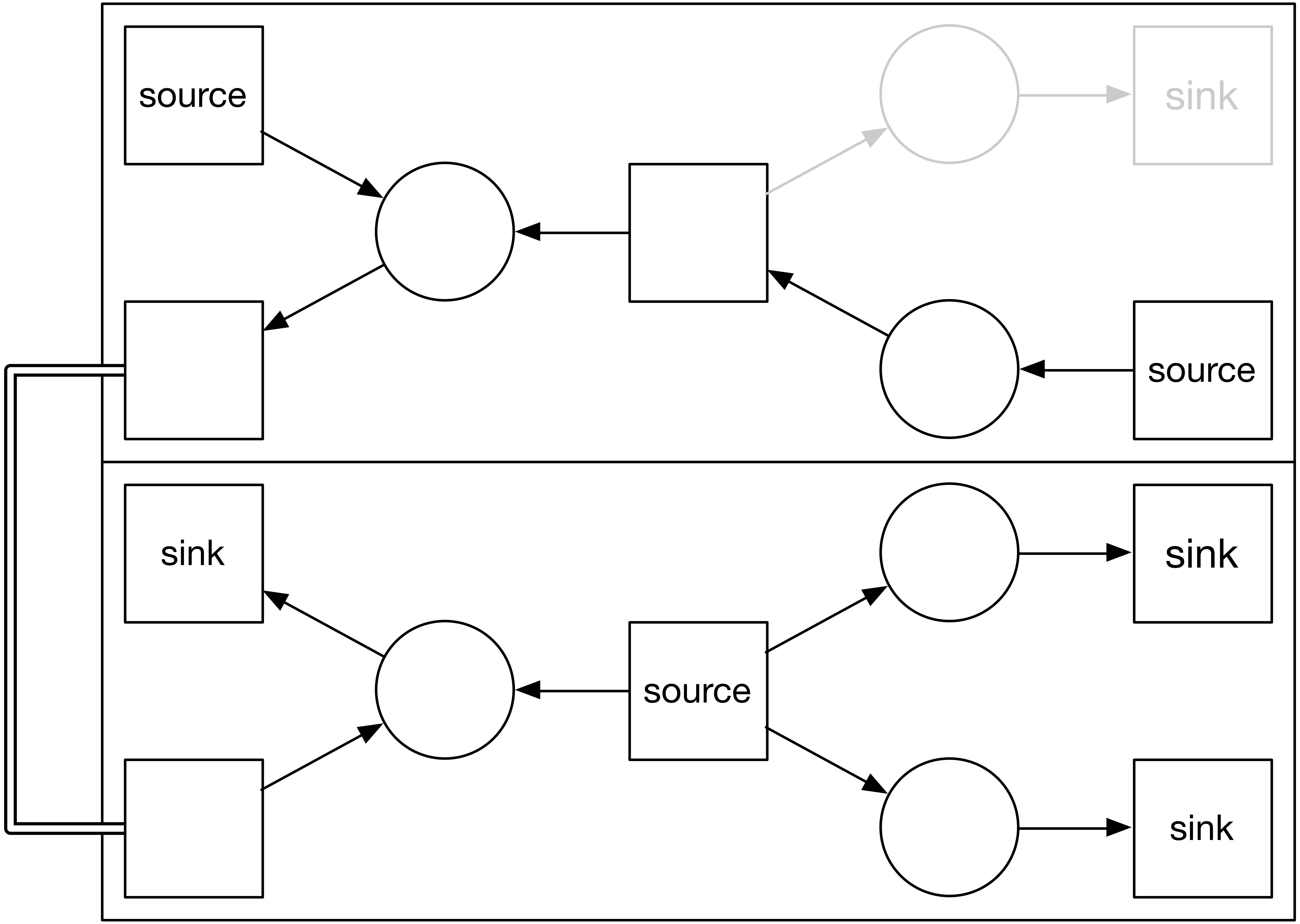
Property Model



Property Models

- Reflowing a property model doesn't require all relationships to be resolved
  - The task representing them can still be executing concurrently
- This creates a single dependency graph that is appended to for each new flow and is pruned and *unravels* as tasks are complete

Property Model



Final Thoughts

- Perhaps representing such systems *as if* it where imperative code is not the correct approach
- Instead the a graph description can be compiled and statically validated

- Slides and code from talk:
- https://github.com/sean-parent/sean-parent.github.io/wiki/Papers-and-Presentations

- Experimental future library:
- https://github.com/stlab/libraries/tree/develop

No raw synchronization primitives

Communicating Sequential Tasks

Better Code

Adobe